



H-JTAG
USER MANUAL

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H-JTAG

USER MANUAL

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Support Forum

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Preface

A. About this manual

H-Jtag user manual introduces how to configure and use H-Jtag and H-Flasher. Some illustrative examples are also given in this manual for reference. For more information, please visit www.hjtag.com or forum.hjtag.com.

B. Using this manual

This manual is intended to assist user in the use of H-Jtag and H-Flasher. If you are a beginner, this manual is a good quick start guide. If you are not a beginner, you can use this manual as a reference and read it selectively.

C. Feedback

If you find any error or omission in this document, please contact us. Any suggestions and comments are welcome. The contact email address is twentyone@hjtag.com.

Chapter 1 H-Jtag Introduction

1.1 About H-Jtag

H-Jtag is a debug agent, likes the popular Multi-ICE. H-Jtag includes three tools, H-Jtag server, H-Flasher and H-Converter (Fig 1-1). H-Jtag server acts as a debug agent, while H-Flasher acts as a flash programmer. H-Converter is a conversion tools, which supports common file formats like BIN, HEX and ELF.



Fig 1-1 H-JTAG Structure

H-Jtag supports the debug of all the CORTEX-M3, ARM7, ARM9, and XSCALE based chips and can be used with most of the popular debuggers, for example ADS, RVDS, IAR and KEIL/MDK. H-Jtag provides flexible configuration, with which H-Jtag can work with Wiggler, SDT-Jtag, other user-defined JTAG interface boards and USB H-JTAG emulator. The included H-Flasher supports the programming of most common flash chips. With H-Jtag, it is easy to build up a debug platform. Summed up, H-Jtag has following features.

1. Support RDI 1.5.0 and RDI1.5.1;
2. Support all CORTEX-M3, ARM7, ARM9 and XSCALE chips;
3. Support THUMB and ARM instructions;
4. Support Little-Endian and Bit-Endian;
5. Support Semihosting;
6. Support Wiggler, SDT-Jtag, user defined JTAG interface boards and USB H-JTAG emulator;
7. Support WINDOW 9.X/NT/2000/XP/VISTA;
8. Support the programming of most common On-Chip flash, Nor flash and Nand flash chips;
9. Support auto flash download for LPC1700/2000, AT91SAM, LUMINARY and STM32F series;

1.2 Communication Structure

H-Jtag supports RDI interface from ARM Limited. Through the RDI interface, H-Jtag can support most of the popular debuggers. The connection for debugging is shown in Fig 1-2.

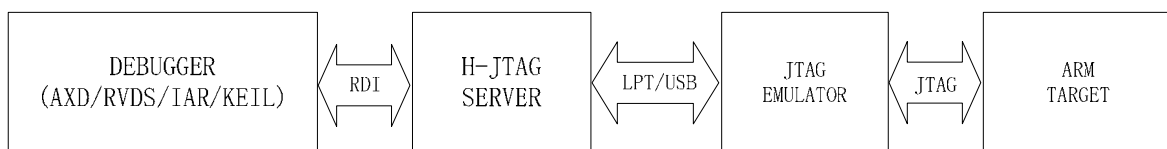


Fig 1-2 Connection for Debugging

Debuggers communicate with H-Jtag server via RDI. H-Jtag server accesses the JTAG port of target system through the JTAG controller connected to LPT/USB. With proper configuration, H-Jtag can work with different LPT JTAG emulators or H-JTAG USB JTAG emulator.

Besides debugging, H-Flasher can download data/program into flash chip. Currently, H-Flasher supports most common on-chip flashes and external flashes. In the future, H-Flasher will support more and more chips. For programming, the connection between H-Flasher and H-Jtag server is shown in Fig 1-3.

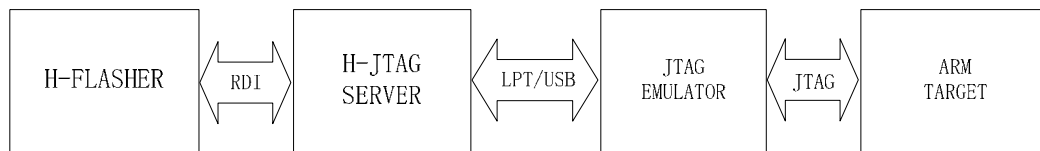


Fig 1-3 Connection between H-Flasher and H-Jtag Server

As shown in the above figure, H-Flasher also talks to H-Jtag server via RDI. The communication is similar to that for debugging.

1.3 Supported ARM Cores

H-JTAG supports the debugging and programming of all the common ARM cores.

CORTEX-M3

ARM7TDMI, ARM7TDMI-S, ARM720T, ARM740T

ARM9TDMI, ARM920T, ARM922T, ARM940T, ARM926EJ-S, ARM946E-S, ARM966E-S

ARM1136, ARM1176

PXA21X, PXA25X, PXA27X, PXA3XX, IXP4XX

1.4 Supported IDEs

H-JTAG supports all the popular IDEs, which include SDT2.5, ADS1.2, RVDS2.0, RVDS2.2, KEIL/MDK and IAR Embedded Workbench.

Chapter 2 Installation and GUI

This chapter introduces both the installation/uninstallation and the GUI. For the detailed configurations, please refer to Chapter 4-7.

2.1 Installation

User can download the latest version installation file from www.hjtag.com. Normally, the downloaded file is zipped and need to be unzipped first. After unzipped, user can get the installation exe file h-jtag.exe. By double clicking the exe file, the installation can be started.

First, user will see the welcome dialog, as shown in Fig 2-1. Click “Next” and go to next step.



Fig 2-1 Installation Step-1

In the second step, user will see the license agreement, as shown in Fig 2-2. Please read the agreement carefully. To accept it, tick “I agree with the above terms and conditions.” Then click “Next”. Otherwise, click “Exit” to exit the installation.

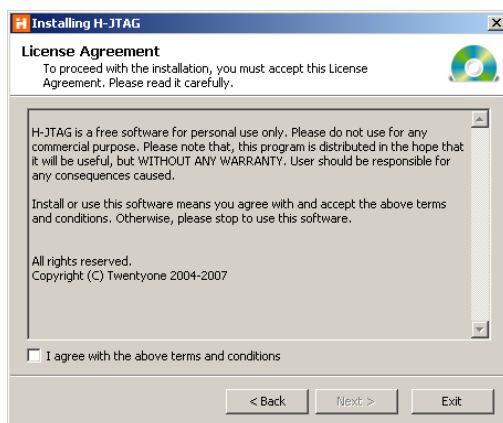


Fig 2-2 Installation Step-2

In the third step, user will see the destination folder dialog (shown in Fig 2-3). In this dialog, user can choose the destination folder. After choosing the destination folder, click “Next” and go to next step.

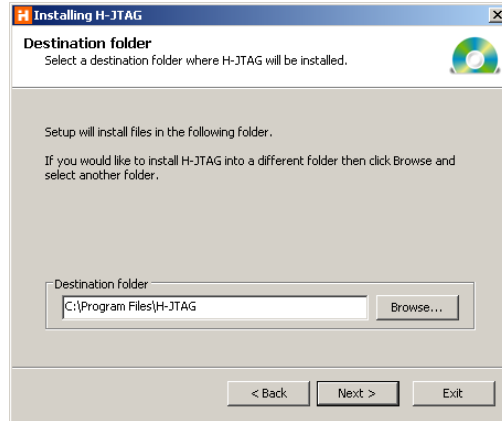


Fig 2-3 Installation Step-3

In step-4, the progress dialog shown in Fig 2-4 will be seen. This dialog shows the progress of installation. In this step, H-Jtag will install all the files automatically.

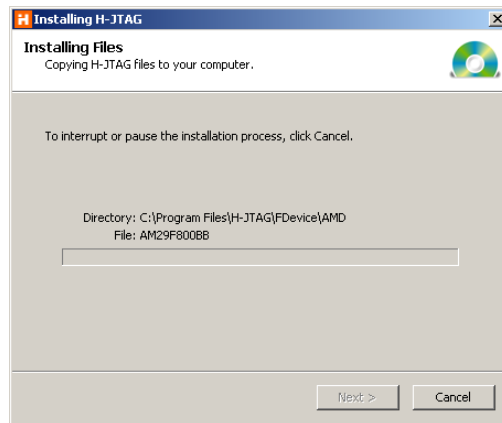


Fig 2-4 Installation Step-4

In the final step, user will see the dialog shown in Fig 2-5. The dialog indicates that H-Jtag has been installed successfully. To complete the installation, click "Finish".



Fig 2-5 Installation Step-5

After the installation, shortcuts will be created on the desktop and the start menu respectively. The shortcuts are shown in Fig 2-6.

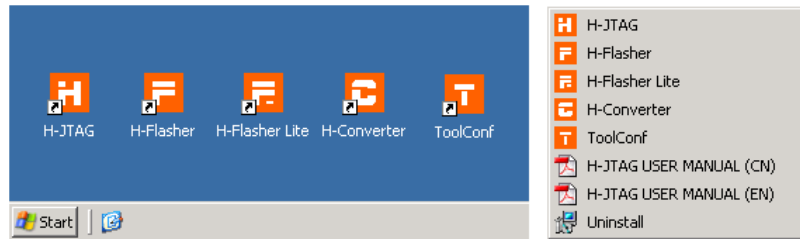


Fig 2-6 Shortcuts of H-Jtag

NOTE: The driver for H-JTAG USB emulator need to be installed manually. Please refer to Chapter-3 on how to install the driver.

2.2 Uninstallation

To uninstall H-Jtag, please run unsta11.exe from the start menu. This program will uninstall H-Jtag automatically. During the process, please follow the instructions to perform the uninstallation.

2.3 GUI of H-Jtag

The main window of H-Jtag is shown in Fig 2-7. In the figure, (1) is the menu, (2) is the toolbar, (3) is the detected ARM core, (4) is the device ID and (5) shows the connected debugger, RDI version and hardware interface.

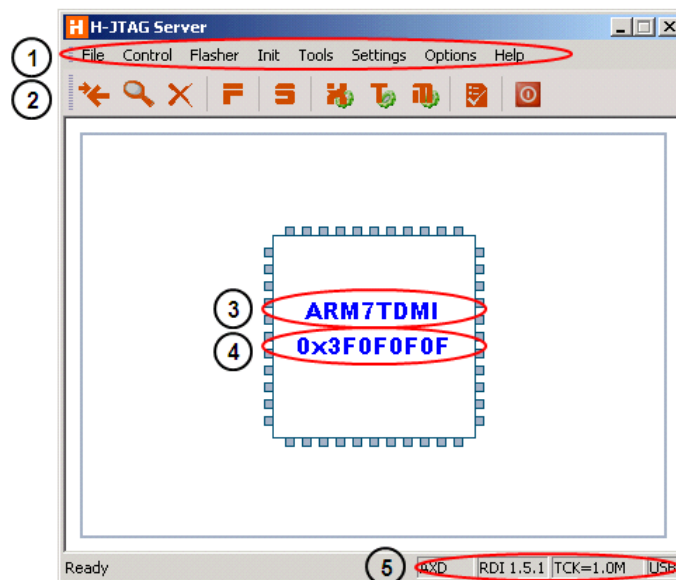


Fig 2-7 Main window of H-Jtag

The menu includes all the operations and configurations, and the toolbar includes most of the common ones. When a connected target is detected, H-Jtag displays the ARM core and 32-bit device ID in the middle of the main window. When no target is detected or the target is unrecognized, H-Jtag displays UNKNOWN.

2.3.1 Menu of H-Jtag

- File Menu, as shown in following figure.



Fig 2-8 File Menu

-  Exit – Exit H-Jtag.

- Control Menu, as shown in Fig 2-9.

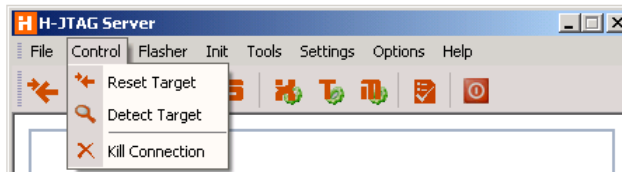







Fig 2-9 Control Menu

-  Reset Target – Reset target
-  Detect Target – Detect target
-  Kill Connection – Kill current connection

- Flasher menu, as shown in Fig 2-10.





Fig 2-10 Flasher Menu

-  Start H-Flasher – Start H-Flasher
-  Auto Download – Enable/Disable auto flash download

- Init Menu, as shown in Fig 2-11.



Fig 2-11 Init Menu

-  Init Script – Configure init script
-  Auto Init – Enable/Disable auto init

- Tools Menu, as shown in Fig2-12.

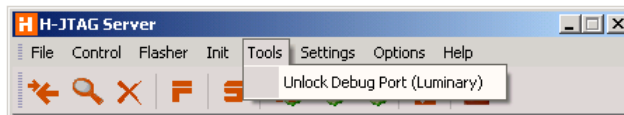


Fig 2-12 Tools Menu

- 🚦 Unlock Debug Port – Unlock debug port for Luminary series

- Settings Menu, as shown in Fig2-13.

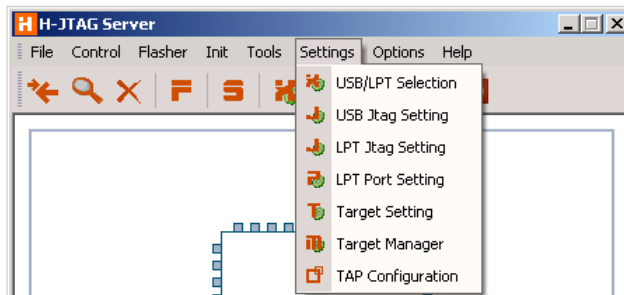


Fig 2-13 Settings Menu

- 🚦 USB/LPT Selection – Selection of hardware interface
 - 🚦 USB JTAG Setting – JTAG setting for USB
 - 🚦 LPT JTAG Setting – JTAG setting for LPT
 - 🚦 LPT PORT Setting – Port setting for LPT
 - 🚦 Target Setting – Target setting
 - 🚦 Target Manager – Device ID manager
 - 🚦 TAP Configuration – TAP configuration

- Options menu, as shown in Fig2-14.

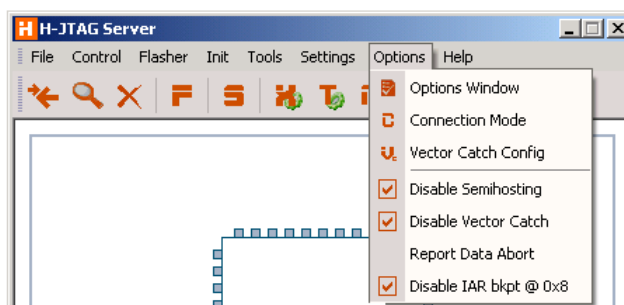


Fig 2-14 Options Menu

- 🚦 Options Window – Open the main window of options
 - 🚦 Connection Mode – Selection of different connection modes
 - 🚦 Vector Catch Config – Configuration for vector catch
 - 🚦 Disable Semihosting – Disable semihosting function
 - 🚦 Disable Vector Catch – Disable vector catch function
 - 🚦 Report Data Abort – Enable/Disable report of data abort

- ✚ Disable IAR bkpt @ 0x8 – Disable the breakpoint set at 0x8 by IAR

- Help menu, as shown in Fig 2-15.

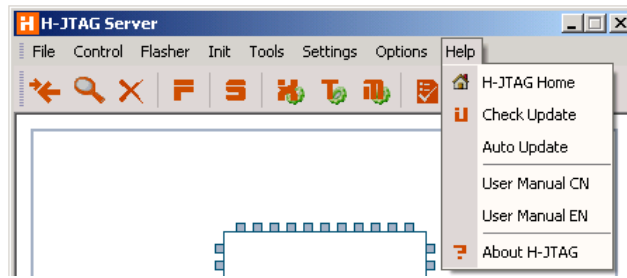


Fig 2-15 Help Menu

- ✚ H-JTAG Home – Visit H-Jtag homepage
- ✚ Check Update – Check for updates
- ✚ Auto Update – Enable/Disable automatic check for updates
- ✚ User Manual CN – Chinese user manual
- ✚ User Manual EN – English user manual
- ✚ About H-JTAG – Information about H-Jtag

2.3.2 H-Jtag Toolbar

This section gives a brief introduction to the toolbar. The toolbar of H-Jtag includes most of the common operations and settings. The toolbar is shown in Fig 2-16.



Fig 2-16 Toolbar of H-Jtag

The definition and function of each button is shown below.

- ✚ Reset target
- ✚ Detect target
- ✚ Kill current connection
- ✚ Start H-Flasher
- ✚ Configure init script
- ✚ Selection of USB/LPT
- ✚ Configure target
- ✚ Device ID manager
- ✚ Open the option window
- ✚ Exit H-Jtag

2.3.3 H-Jtag Tray Menu

When H-Jtag is minimized, the main window is hidden automatically and only an icon is shown in the system tray. The main window can be restored by left clicking the icon. Right clicking the icon, the system tray menu is popped up. The tray menu includes some common operations and settings.

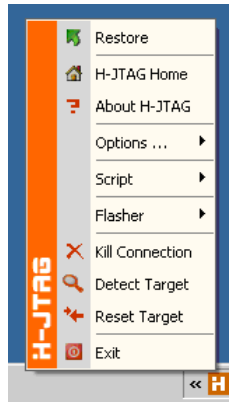


Fig 2-17 System Tray Menu of H-Jtag

The tray menu is defined as follows.

- 🚩 Restore – Restore the main window
- 🚩 H-JTAG Home – Visit homepage of H-Jtag
- 🚩 About H-JTAG – Information about H-Jtag.
- 🚩 Options – Options menu
- 🚩 Script – Script menu
- 🚩 Flasher – H-Flasher menu
- 🚩 Kill Connection – Kill current connection
- 🚩 Detect Target – Detect target
- 🚩 Reset Target – Reset target
- 🚩 Exit – Exit H-Jtag

2.4 GUI of H-Flasher

The main window of H-Flasher looks like Fig 2-18. In the figure, (1) is the menu, (2) is the program wizard and (3) is the configuration area. In the wizard, user can go to different steps. According to the selection on the wizard, the configuration area has different displays. For detailed information, please refer to Chapter 5.

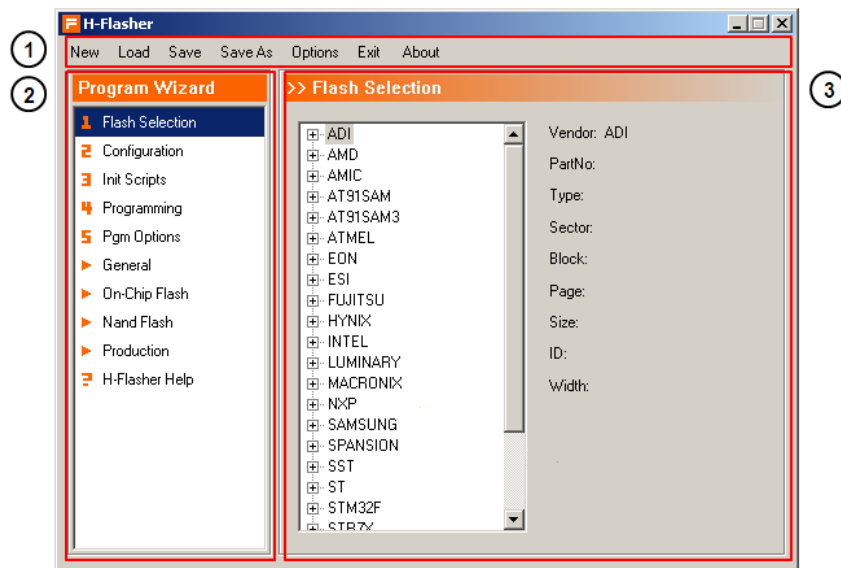


Fig 2-18 Main Window of H-Flasher

2.4.1 Menu of H-Flasher

The menu of H-Flasher is shown in Fig 2-19.

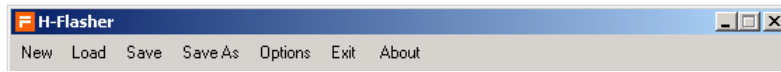








Fig 2-19 Menu of H-Flasher

The menu is defined as follows.

-  Load – Load configuration file
-  Save – Save current configuration
-  SaveAs – Save current configuration as another file
-  Options – Select different options
-  Exit – Exit H-Flasher
-  About – Information about H-Flasher.

2.4.2 H-Flasher Tray Menu

When H-Flasher is minimized, the main window is hidden automatically and only an icon is shown in the system tray. The main window can be restored by left clicking the icon. Right clicking the icon, the system tray menu is popped up.

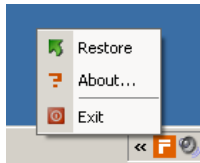





Fig 2-20 H-Flasher Tray Menu

The tray menu is defined as follows.

-  Restore – Restore the main window
-  About – Information about H-Flasher
-  Exit – Exit H-Flasher

2.4.3 H-Flasher Program Wizard

The program wizard includes 5 steps and 1 help section. This section gives a brief introduction to the program wizard.

(1) Flash Selection

Flash selection is the first step of the program wizard, as shown in Fig 2-21. In this step, all the supported flash chips are categorized by vendors. User needs to specify the target flash chip. When a chip is selected, the basic information of the chip is displayed on the right side.

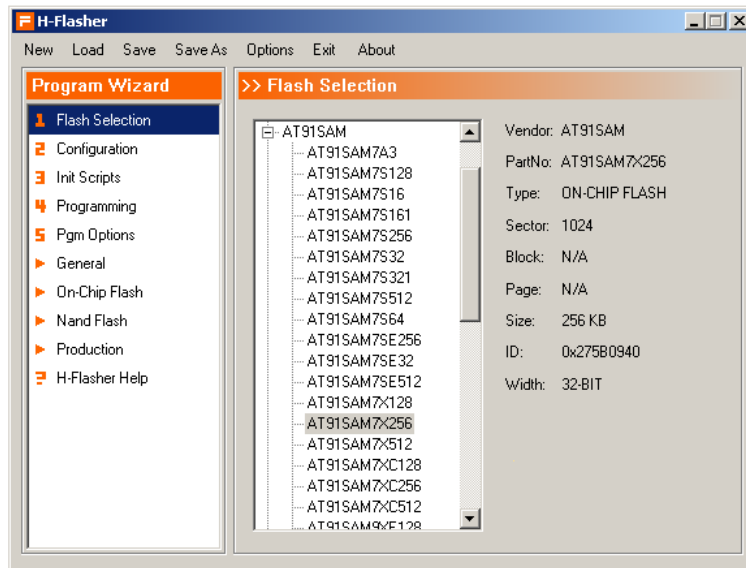


Fig 2-21 Program Wizard – Flash Selection

(2) Configuration

Configuration is the second step of the wizard. The display is shown in Fig 2-22. In this step, user needs to provide the basic addressing information, for example, bit width, flash start address, RAM start address, XTAL, init TCK and program TCK. All this information is a must. In this step, if an input area is in gray, it means no input is required. Normally, the information is fixed for on-chip flash.

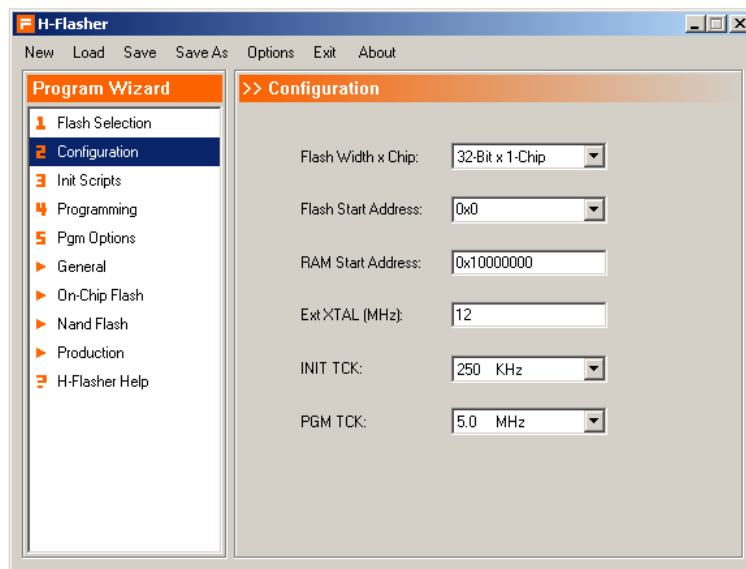


Fig 2-22 Program Wizard – Configuration

(3) Init Script

Init script is the third step of the programming wizard. In this step, the display is shown in Fig 2-23. User can input any scripts for initialization. During the programming, H-Flasher first executes the provided init script in order to initialize the target system. For on-chip flash, the initialization has been included in the flash driver, so no additional init script is needed. In this case, the buttons for editing are all disabled.

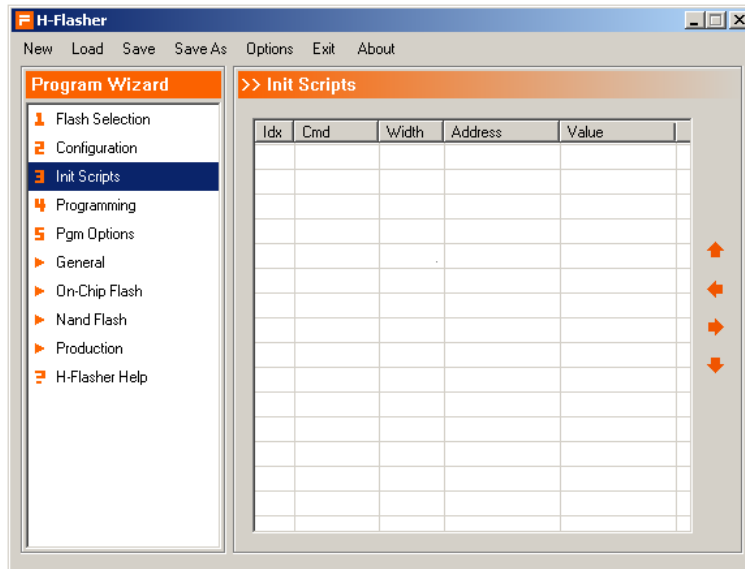


Fig 2-23 Program Wizard – Init Script

(4) Programming

Programming is the fourth step of the wizard. In this step, user can operate on the target flash, like reset target, check flash, write/erase flash, verify and check if it is blank. Depends on the type of the selected flash, user can see different dialogs, as shown in Figs 2-24, 2-25 and 2-26.

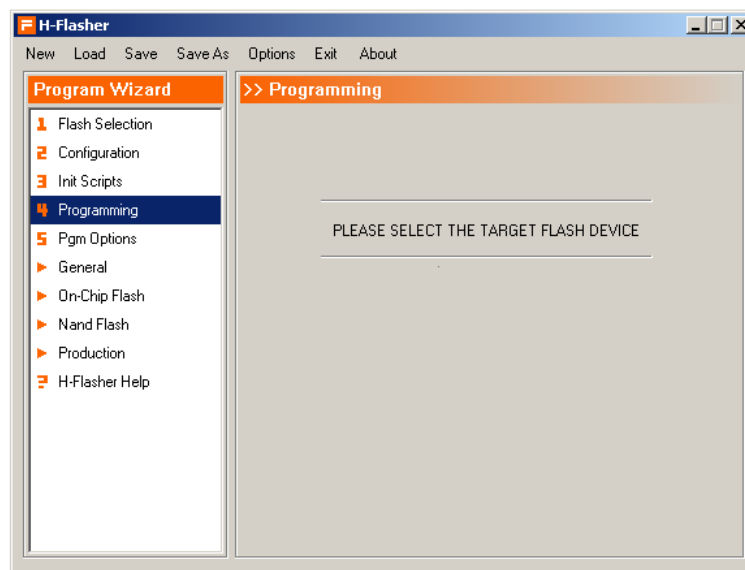


Fig 2-24 Program Wizard – Programming (No Chip Is Selected)

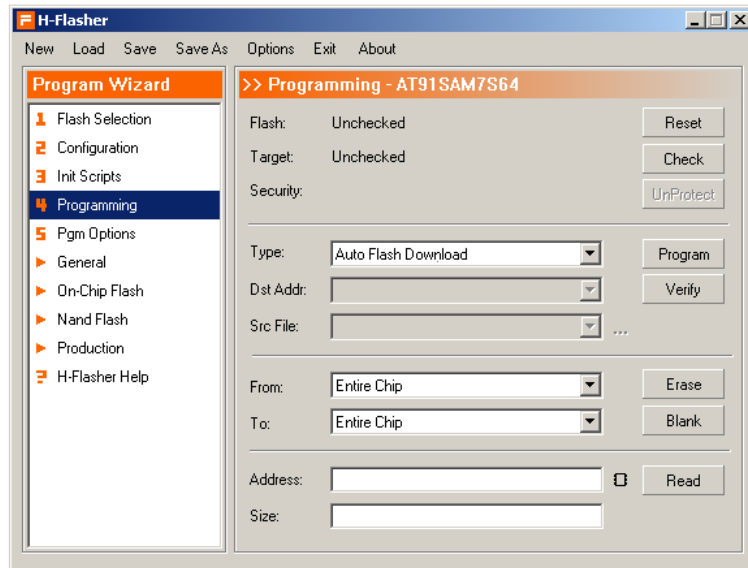


Fig 2-25 Program Wizard – Programming (On-Chip Flash or Nor Flash Is Selected)

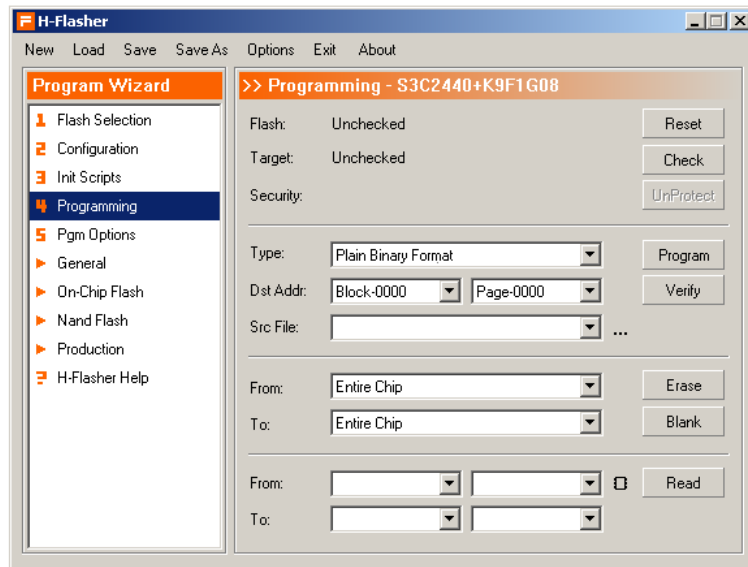


Fig 2-26 Program Wizard – Programming (Nand Flash Is Selected)

(5) Program Options

This is the fifth step of the programming wizard. As shown in following figures, user can make different selections based on the selected FLASH chip.

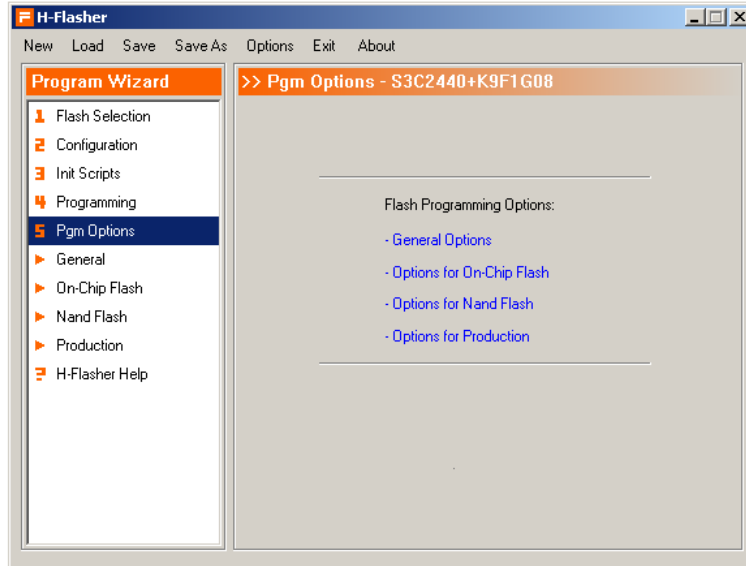


Fig 2-27 Program Wizard – Program Options

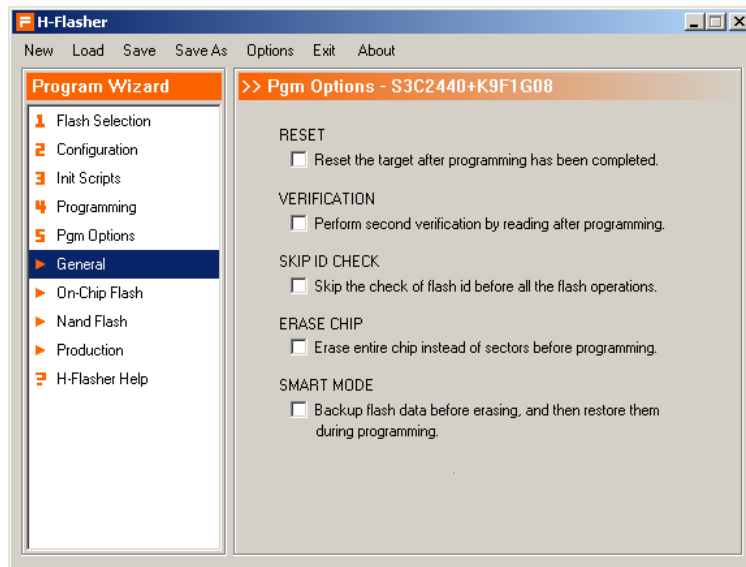


Fig 2-28 Program Wizard – General Options

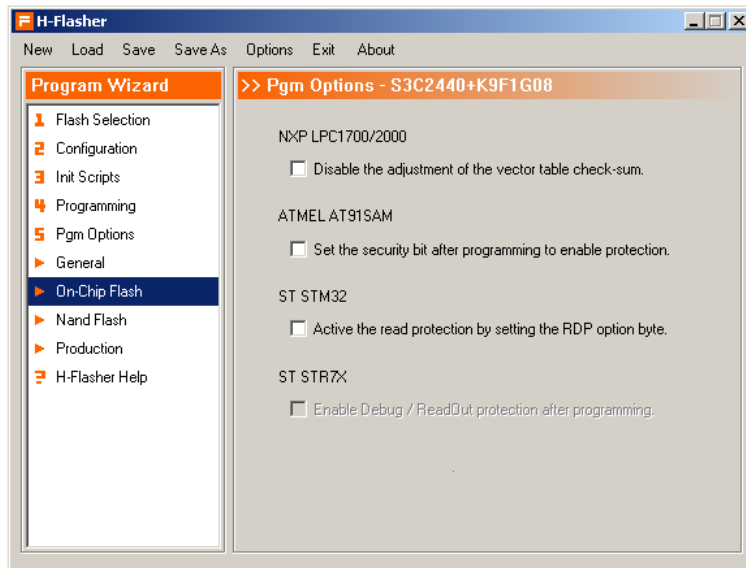


Fig 2-29 Program Wizard – On-Chip Flash Options

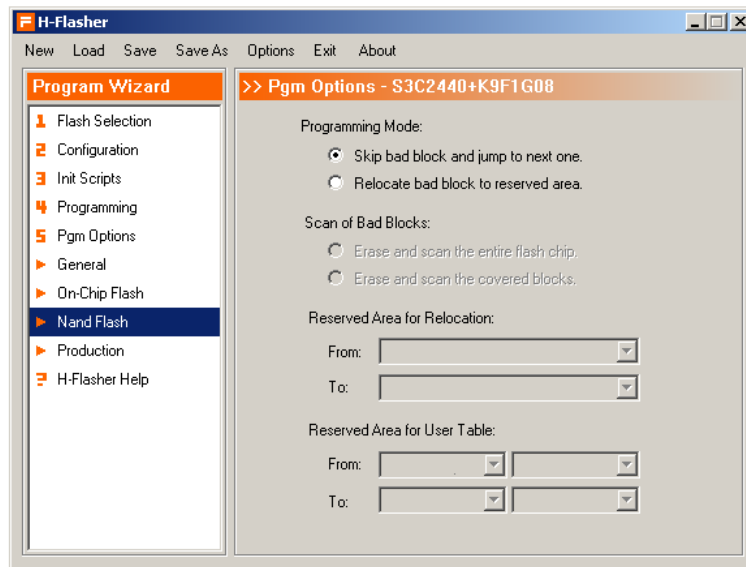


Fig 2-30 Program Wizard – Nand Flash Options

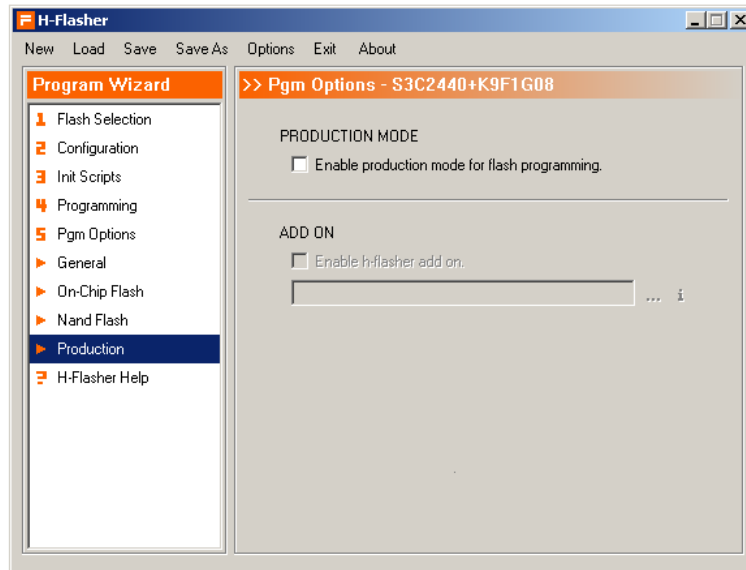


Fig 2-31 Program Wizard – Production Options

(6) Help

In the wizard, a help section is also included. This help section has the basic information on how to use H-Flasher.

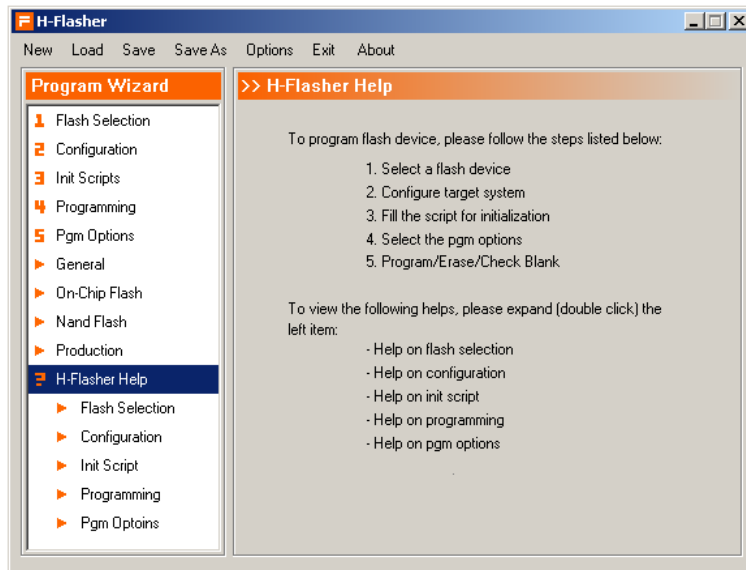


Fig 2-32 Program Wizard - Help

Chapter 3 H-JTAG USB Emulator

This chapter introduces the hardware interface and some hardware features of H-JTAG USB emulator and the installation of its driver.

3.1 Hardware Features and Interface

H-JTAG USB emulator is a high-performance ARM in circuit emulator, which provides 10K~15M Hz JTAG clock. The maximum download speed is up to 750KB/S and the maximum upload speed is up to 550KB/S.

Hardware Features:

- USB 2.0 Controller+ FPGA design
- High speed USB 2.0
- Powered through USB
- 10K ~ 15MHz JTAG speed
- 20-PIN std JTAG interface
- Wide target voltage 1.8 ~5.0V

✚ **Note:** H-JTAG USB emulator only supports high-speed USB 2.0 interface.

Maximum RAM Read/Write Speed:

ARM7 -	Max write speed 750KB/S Max read speed 550K/S
ARM9 -	Max write speed 750KB/S Max read speed 520K/S
XSCALE -	Max write speed 750KB/S Max read speed 520K/S
CORTEX-M3 -	Max write speed 420KB/S Max read speed 340K/S

✚ **Note:** The above data is for reference only. The actual speed may be different.

Appearance:

The appearance of the emulator is shown in Fig 3-1. The USB interface locates on the left side and the 20-pin JTAG interface locates on the right side.

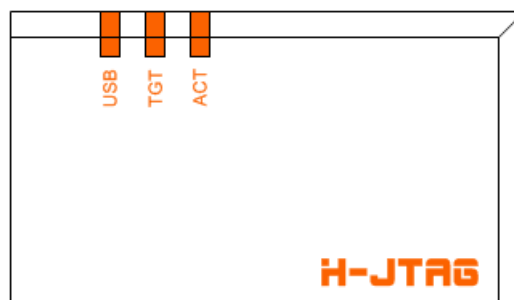


Fig 3-1 Appearance of Emulator

There are three LED indicators on the upper side, which are used to indicate the USB power, target power and JTAG activity respectively.

- A. USB: Represent the USB power.
- B. TGT: Indicate if target is connected appropriately.
- C. ACT: Indicate JTAG activity when flashing.

The H-JTAG emulator equipped with a standard 20-pin JTAG interface. The definitions of signals are shown in Fig 3-2.

VREF	1	2	NC
nTRST	3	4	GND
TDI	5	6	GND
TMS	7	8	GND
TCK	9	10	GND
NC	11	12	GND
TDO	13	14	GND
nSRST	15	16	GND
NC	17	18	GND
NC	19	20	GND

Fig 3-2 JTAG interface of H-JTAG emulator

3.2 Different Emulator Versions

H-JTAG USB emulator has three versions, which are personal edition, standard edition and professional edition. These three editions can be differentiated by colors, as shown in Fig 3-3.



(a) Personal Edition

(b) Standard Edition

(c) Professional Edition

Fig 3-3 Different emulator editions

The differences of functionalities are listed in Table 3-1.

H-Jtag Version		Personal	Standard	Professional
Speed	Download	5 x LPT	750KB/S	750KB/S
	Upload	5 x LPT	550KB/S	550KB/S
ARM CORE	ARM7	YES	YES	YES
	ARM9	YES	YES	YES
	CORTEX-M3	YES	YES	YES
	XSCALE	NO	YES	YES
	ARM11	NO	NO	YES
	PXA3XX	NO	NO	YES
Supported IDE		ADS1.2 RVDS KEIL/MDK IAR		
Supported OS		NT/WIN2000/WINXP/VISTA		

Table 3-1 Differences of functionalities

3.3 Driver Installation

After the installation of H-JTAG software, a folder named Driver is created under the installation directory. This folder includes the drivers for different WINDOWS platforms. Next, user needs to install the driver for emulator. This section shows how to install the driver step by step.

First, connect the emulator to PC via a USB cable. The PC will show a new hardware wizard dialog soon, which looks like Fig 3-3.



Fig 3-4 New hardware wizard

In the wizard, choose Install from a list or specific location, as shown in Fig 3-4. Then, click Next.



Fig 3-5 Install from list

Next, a search and installation options dialog (Fig 3-5) will be shown. In this dialog, choose Search for the best driver in these locations. De-select Search removable media. Select Include this location in the search. Meanwhile, use the Browse button to locate the Driver folder under H-JTAG installation directory. Then, click Next.

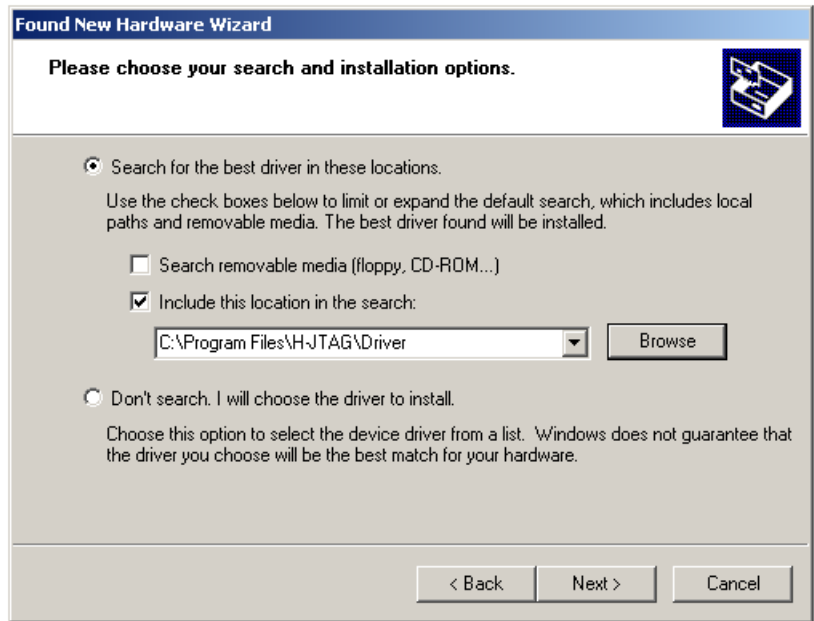


Fig 3-6 Search and installation options

Soon, a confirm dialog will be popped up after a quick search. In the following picture, click Continue Anyway to proceed with the installation.

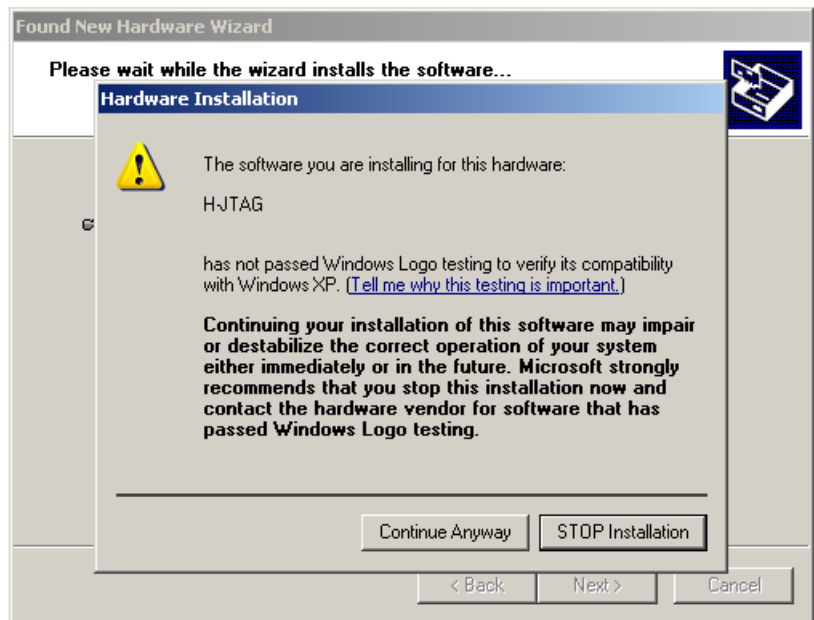


Fig 3-7 Confirm dialog

Later, a completing dialog will be seen. If the installation is completed successfully, the dialog looks like Fig 3-7.



Fig 3-8 Completing dialog

After the above steps, H-JTAG will be listed as a device in the device manager, as shown in Fig 3-8. If you can't see H-JTAG in the device manager, please try to install the driver again.

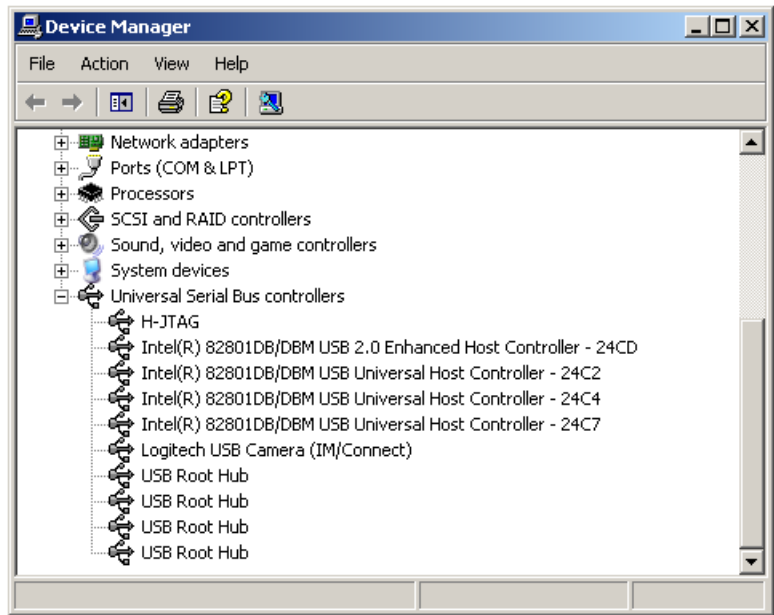


Fig 3-9 Device manager

Chapter 4 Configure H-Jtag

This chapter introduces how to configure and use H-Jtag in details. Meanwhile, some simple examples are given for reference.

4.1 Detect Target

Before detection, please connect the JTAG emulator to the USB or parallel port and connect target to the JTAG emulator. During the start up, H-Jtag tries to detect the target automatically. After H-Jtag is started up, user can click the detect button to detect target. If the target is detected successfully, the ARM core and device ID are displayed in the middle of the main window. Otherwise, please check the configuration and hardware connection.

4.2 Reset Target

User can reset target via H-Jtag. For a standard JTAG interface, two independent reset signals, system reset (nSRST) and JTAG/TAP reset (nTRST), are defined. With these two reset signals, H-Jtag can perform system reset or JTAG/TAP reset. User can choose to perform system reset, JTAG/TAP reset or both. H-Jtag provides different options. Please refer following section for details.

Note:

Some LPT based JTAG emulator doesn't provide system reset signal, so H-Jtag can't perform system reset on target. The target can only be reset manually. Some LPT based JTAG emulator connects the system reset and JTAG/TAP reset together. In this case, any reset operation actually asserts both signals.

4.3 Auto Flash Download

Some ARM chips come with internal flash and RAM, so no external memory is needed. For this kind of chips, for example LPC2000, AT91SAM7, LUMINARY CORTEX-M3 and STM32F series, H-Jtag supports auto flash download. With auto flash download, program can be directly downloaded or written to flash for debugging, just like debug in RAM/SDRAM. To use auto flash download, please enable the auto download option as shown in Fig 4-1. Meanwhile, please choose appropriate target flash in H-Flasher. During downloading, H-Jtag will determine where the program should be downloaded according to the destination address. For those need to be written to flash, H-Jtag will call H-Flasher to achieve it automatically.

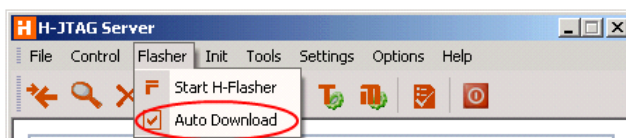


Fig 4-1 Auto Flash Download

Note:

Normally, auto flash download only supports on-chip flash, like LPC2000 and AT91SAM7. The reason is that the memory systems of these chips are relatively simpler. For chips supports complicated memory configuration, like MMU/REMPA, please write the program into flash using H-Flasher before starting debug.

Note:

H-Flasher Lite does not support Auto Flash Download. To use Auto Flash Download, please run H-Flasher.

4.4 Initialization Script

For most systems, initialization need to be completed after powered up. The initialization of memory system is one of these. Most of the time, flash and on-chip SRAM can be accessed directly after powered up, but this is not the case for external SDRAM. External SDRAM needs to be initialized before it can be accessed correctly. For beginners, one of the common problems is that the program can not be downloaded into external SDRAM correctly. The reason is that the external SDRAM is not initialized properly. There are two methods to initialize the target system. The first one is to write an initialization program into flash. This program will be executed right after the target is powered up. So, the target is initialized automatically after powered up and is ready for use. The second one is to use initialization script. For the convenience of user, H-Jtag defines some script commands and provides auto initialization. To use auto init, user needs to input or load proper initialization scripts and enables auto init. If auto init is enabled, H-Jtag will execute the provided initialization scripts whenever a connection is opened by debugger. The script editor is shown in following figure. For the details on the initialization script, please refer to Chapter 6.

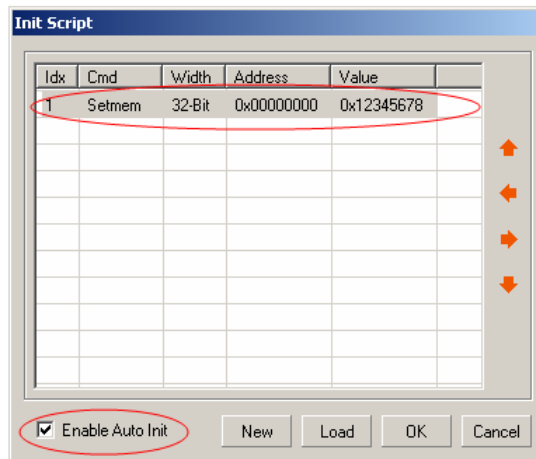


Fig 4-2 Script Editor

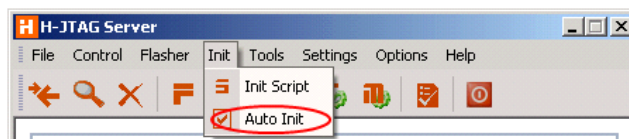


Fig 4-3 Auto Init

Note:

If auto init is enabled in H-Jtag server, initialization scripts must be provided. Otherwise, H-Jtag would notify user with error message “Can’t open specified init script.”

Note:

For the detailed definition of script commands, please refer to Chapter 6.

4.5 USB/LPT Interface Selection

H-Jtag supports both LPT based JTAG emulator and USB based H-JTAG emulator. User should select the right hardware interface accordingly.

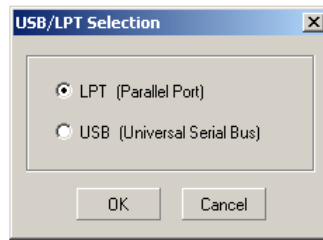


Fig 4-4 USB/LPT Interface Selection

4.6 JTAG Configuration

This section introduces the definition of JTAG interface, connection to USB/LPT port and the configuration of JTAG.

4.6.1 JTAG Signals

JTAG is a test standard proposed by IEEE. For ARM debugging, JTAG is used as the interface. The ARM JTAG interface defines 7 signals, TMS, TCK, TDI, TDO, RTCK, nSRST and nTRST. For the debugging of ARM7 and ARM9, TMS, TCK, TDI and TDO are indispensable, while RTCK, nSRST and nTRST are optional.

 **Note:**

For XScale, both nSRST and nTRST signals are indispensable. In addition, these two signals should be separate. Otherwise, debugging can not be proceeded.

4.6.2 JTAG Connection

The typical JTAG connection looks like Fig 4-5. The JTAG emulator connects to both the USB/LPT and the target. H-JTAG generates JTAG signals via the JTAG emulator to control the target. The JTAG interface between JTAG emulator and ARM target normally adopts the 14-pin or 20-pin standard. The H-Jtag server and the JTAG emulator can communicate to each other via USB or LPT. When LPT is used, user needs to provide the accurate JTAG configuration and tell H-JTAG exactly how the JTAG emulator is connected to LPT. For the details on how to configure JTAG, please refer to the following sections.

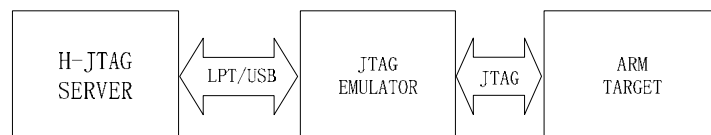


Fig 4-5 JTAG Connection

4.6.3 USB JTAG Setting

H-Jtag USB emulator supports different TCK speeds (25K – 15M Hz). User can choose the appropriate TCK speed in the USB JTAG setting dialog (Fig 4-6). When AUTO TCK is chose, H-Jtag will choose an appropriate TCK speed automatically through testing.

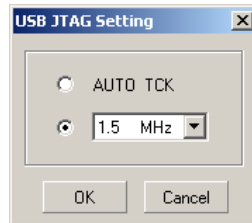


Fig 4-6 USB JTAG Setting

Note:

The TCK speed has direct affect on the debugging performance. Different target system has different highest supported TCK speed. The highest supported TCK speed also depends on the system clock configuration of target system. Appropriate TCK speed should be designated. Over-high TCK speed leads to unpredictable debugging behavior. AUTO TCK may not work under some situation. In this case, please designate a lower TCK speed manually.

4.6.4 LPT JTAG Setting

The LPT based JTAG controller does not have a fixed schematic, even for WIGGLER and SDT-JTAG. Some JTAG emulator comes with nSRST, while others don't have. Some JTAG emulator provides separate nSRST and nTRST, while others connected them together. To support different LPT based JTAG emulators, H-JTAG provides a flexible configuration interface. What user needs to do is tell H-Jtag exactly how the JTAG emulator is connected to LPT.

The LPT provides 8 data bits, D0-D7, as output and several status bits as input. The data bits can be used as JTAG output signals, TMS, TCK, TDI, nSRST and nTRST. Any one of the status bits can be used as input to sample TDO. The JTAG configuration is to specify how the JTAG signals are connected with the data bits and status bits. On some JTAG emulator, the nSRST and nTRST are inverted. These also need to be specified in the JTAG configuration.

Next, let's look at an illustrative example. The schematic of the JTAG emulator used in the example is show in Fig 4-7. The connection between LPT and JTAG can be obtained from the schematic and is listed in following table. Please note that the nTRST signal is inverted and no nSRST signal is provided.

TMS	➡	LPT D1 (PIN3)
TCK	➡	LPT D2 (PIN4)
TDI	➡	LPT D3 (PIN5)
TDO	➡	LPT BUSY (PIN11)
nTRST	⬅	LPT D0 (PIN2) INVERTED
nSRST	×	NOT AVAILABLE

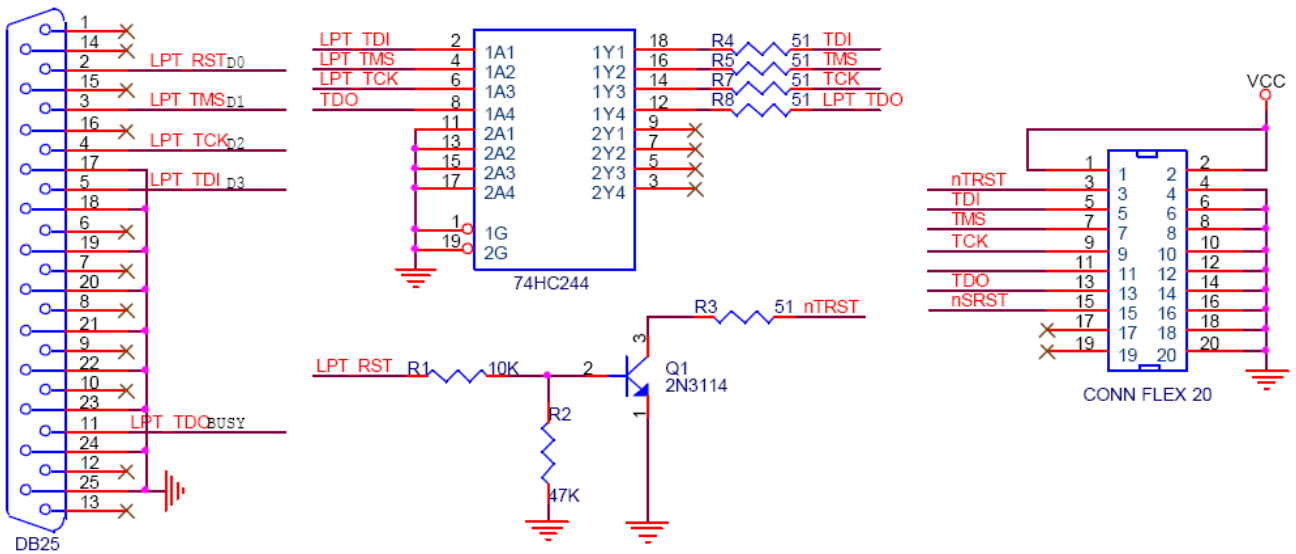


Fig 4-7 Example Schematic of JTAG Emulator

Based on the schematic given in Fig 4-7 and the above analysis, any of the following settings can be used. Both the settings given in Fig 4-8 tell exactly how LPT is connected to the JTAG interface via the JTAG emulator. The given example is only for reference. In practice, please configure according to the schematic of user's own JTAG emulator.

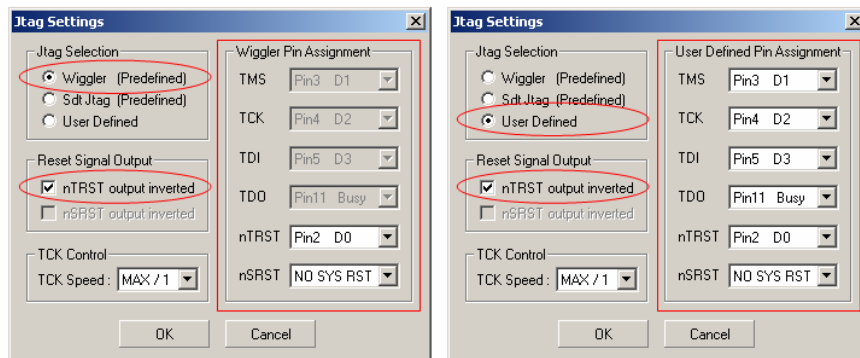


Fig 4-8 Example JTAG Settings

In the dialog of LPT JTAG settings, user can also choose different TCK speed. The selectable TCK speed ranges from MAX to MAX/8. Actually, the parallel port is a low speed interface. In practice, user is suggested to use MAX/1 as the default speed to achieve maximum performance.

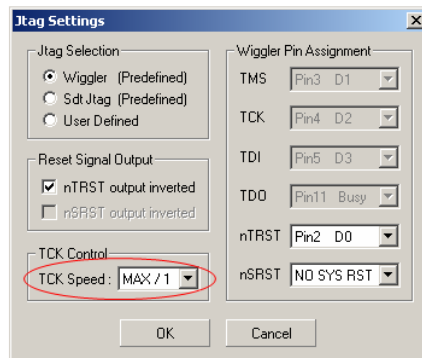


Fig 4-9 Selection of LPT TCK Speed

4.7 LPT Port Setting

For most PCs, the default LPT address is 0x378, but there are some exceptions. In H-Jtag, different port addresses can be specified. The dialog for port setting is shown in Fig 4-10. In the dialog, there also has a test button, which can be used for some simple port read/write test.

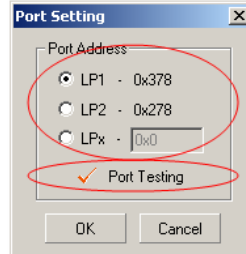


Fig 4-10 LPT Port Setting

4.8 Target Setting

H-Jtag reads device ID via JTAG and determines what the ARM core is. H-Jtag can recognize most of the common chips. For target that can't be recognized, user can designate the ARM core in target settings. The dialog for target settings is shown in Fig 4-11.

Most of the ARM chips support both little endianness and big endianness. With different endianness, the storage of data and instructions are totally different. If the endianness is not specified correctly, the debug definitely goes wrong. User can specify the endianness in target settings (see below).

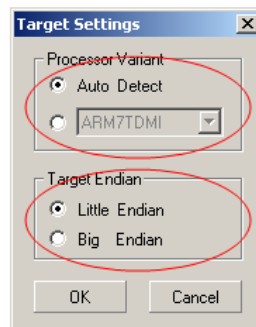


Fig 4-11 Target Setting

4.9 Target Manager

In above section, it is mentioned that H-Jtag determines the ARM core based on the device ID. For chips can't be recognized, user can specify the ARM core manually. User can also add the new device ID into the chip list. After the chip list is updated, H-Jtag can detect and recognize the new chip automatically. All this can be done in the target manager. To add a new device ID, user needs to input the ID and specify the according ARM core. In target manager, user also can delete existing device IDs. The target manager is shown in Fig 4-12.

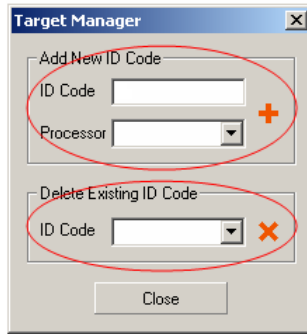


Fig 4-12 Target Manager

Tip:

According to the IEEE-1149 standard, device ID is 32-bit and the lowest bit should be 1. User can tell whether an ID is valid or not based on this. If you have any chip that H-Jtag can't recognize, please email us the device ID and the ARM core. We will update the chip list in next version.

4.10 TAP Configuration

For most ARM chips, the JTAG scan chains are separated. For these chips, the default TAP configuration should be adopted, as shown in Fig 4-13. The figure indicates that no other scan chain is concatenated before and after that of the ARM core.

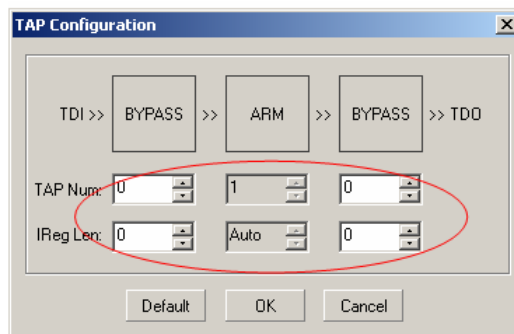


Fig 4-13 Default TAP Configuration

Some chip integrates other scan chains besides that for ARM core. For this kind of chips, user needs to configure TAP accordingly. STR91xF is a chip from ST. This chip integrates several scan chains inside, as shown in Fig 4-14. STR91xF has 3 TAPs, TAP#1, TAP#2 and TAP#3. Among all these TAPs, only TAP#2 is for ARM debugging. TAP#1 and TAP#3 are concatenated before and after TAP#2. The IR length of TAP#1 and TAP#3 is 5-Bit and 8-Bit respectively. For this chip, the TAP configuration should look like Fig 4-15. The TAP configuration shown in Fig 4-15 tells that there is one scan chain before that of the ARM core and its IR length is 5-Bit. In addition, there is another scan chain after that of the ARM core and its IR length is 8-Bit. Based on the TAP configuration, H-Jtag knows how to access the scan chain of the ARM core for debugging.

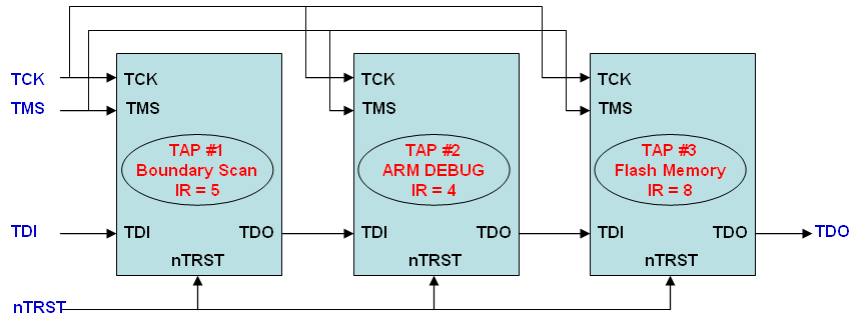


Fig 4-14 STR91xF Scan Chains

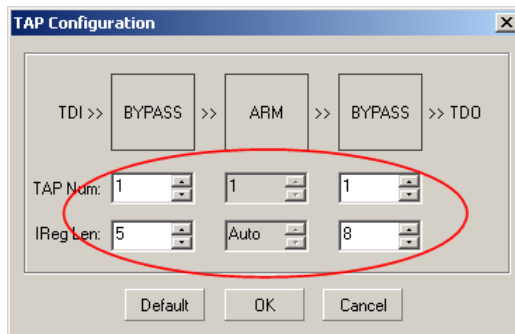


Fig 4-15 TAP Configuration (STR91xF)

4.11 H-Jtag Options

H-Jtag provides some common options. User can make the selection using the main options window or the option menu. The main window of options is shown in Fig 4-16.

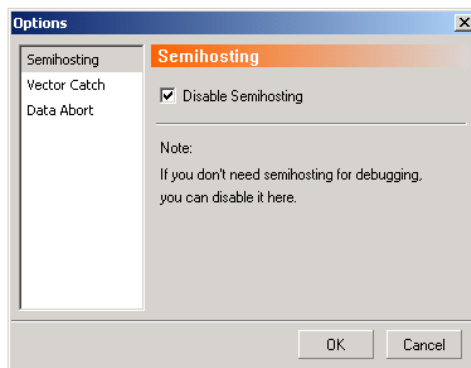


Fig 4-16 Main Window of Options

■ CONNECTION MODE

Different connection modes are defined in H-Jtag. From the connection mode list, user can select different modes as required.

■ VECTOR CATCH CONFIG

H-Jtag server manages the vector catch configuration. In the configuration dialog (Fig 4-17), user can decide which exception(s)/interrupt(s) to be caught during the debugging. When all the flags are cleared, vector catch is disabled automatically. In another case, where the global disable vector catch option is enabled, the configuration on the following dialog is ignored automatically.

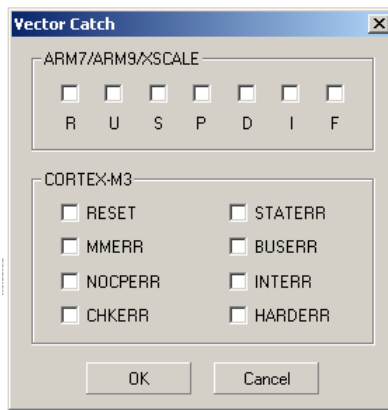


Fig 4-17 Vector Catch Configuration

■ DISABLE SEMIHOSTING

Semihosting is a mechanism for debugging, which can be used for the communication between host and target. Semihosting needs the support from both the emulator and the program running inside the target. In addition, semihosting can only be used for debugging and can't be use in real product. Semihosting also consumes breakpoint resources. So, user is suggested to disable semihosting.

■ DISABLE VECTOR CATCH

Vector catch is used to capture exceptions. When vector catch is enabled in both H-Jtag and debugger, exceptions are notified when they occur. Please note that vector catch also consumes breakpoint resources. So, user is suggested to disable vector catch.

■ REPORT DATA ABORT

During debugging, even when the processor is halted, debugger needs to access the memory of target. Data abort may occur when undefined space or access protected area is accessed. If report data abort is enabled, H-Jtag would notify user when data abort occurs. Otherwise, H-Jtag would only handle the data abort internally without notifying user.

■ DISABLE IAR BKPT @ 0x8

Under IAR, a breakpoint is set at 0x8 during debugging. This breakpoint is invisible in the breakpoint list. When debugging inside flash, user can disable this invisible breakpoint to free a breakpoint unit.

4.12 H-jtag Tools

H-Jtag provides some tool under the Tools menu. In the future, we are going to add more tools to this menu as required by user.

4.13 Check for Updates

User can check for updates by using the check menu. If there is any newer version available, H-Jtag would notify user. User also can visit the homepage of H-Jtag for more information.

Chapter 5 Configure H-Flasher

This chapter introduces how to configure and use H-Flasher in details. At the end of this chapter, two examples are provided for reference.

5.1 H-Flasher Workflow

The workflow of H-Flasher is very simple. As shown in Fig 5-1, the workflow includes four steps: execute init script, download flash driver, check flash ID and operate on flash. These four steps are executed in sequence. If any step goes wrong, the operation is interrupted immediately.

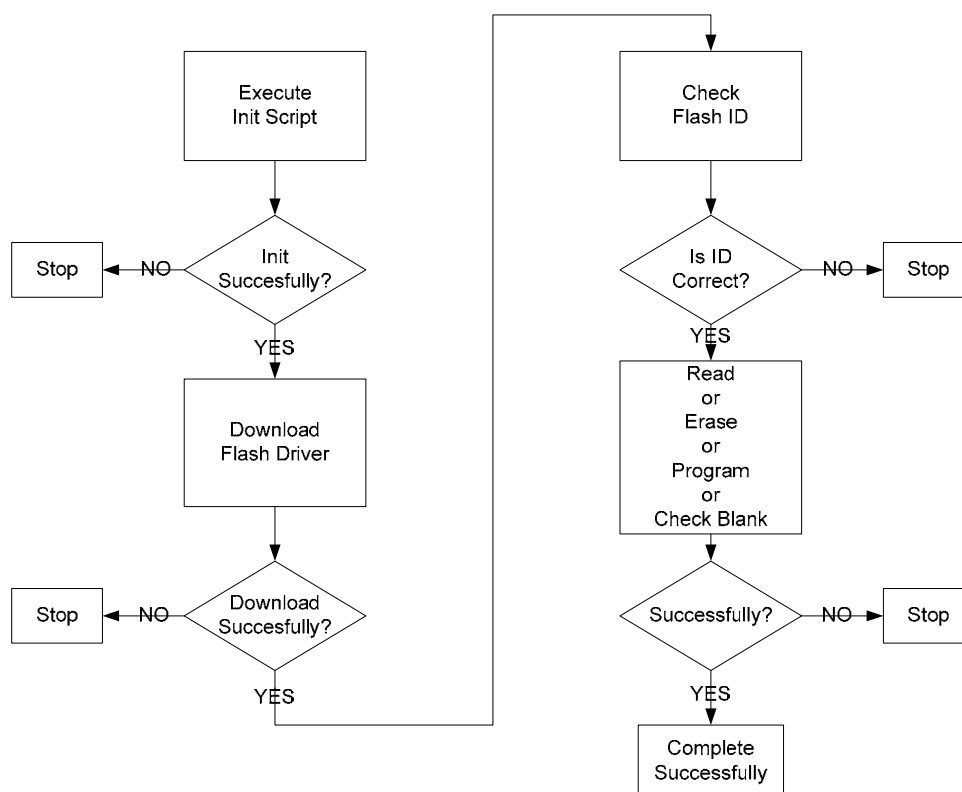


Fig 5-1 Workflow of H-Flasher

5.1.1 Execute Init Script

If init scripts are specified, H-Flasher first executes them to initialize the target. If no init script is specified, or no script is needed, H-Flasher skips this step. If something goes wrong during the initialization, H-Flasher stops immediately and notifies user.

5.1.2 Download Flash Driver

After successful completion of initialization, H-Flasher searches appropriate flash driver according to the selected flash and specified bit width. Then, H-Flasher downloads the flash driver into SRAM/SDRAM based on the designated RAM start address. If the download is successful, go to next step. Otherwise, error out and notify

user with message: Can't download driver to specified address.

5.1.3 Check Flash ID

After the download of driver, H-Flasher checks the flash ID. The purpose is to ensure that the selected flash is the right one and check whether the flash can be accessed by the specified address.

5.1.4 Read/ Erase/ Program/Verify/Check Blank

After the previous three steps have been executed successfully, H-Flasher can perform any operations on target flash as required. The supported operations include read, erase, program, verify and check whether the flash is empty.

5.2 H-Flasher Program Wizard

H-Flasher comes with a program wizard to ease the configuration. User can follow the wizard to complete the configuration.

5.2.1 Flash Section

In this first step, user can select the target flash from the list. User needs to check the information and ensure that the selection is correct. The correct selection is very important, because different flash chips define different command sets.

5.2.2 Configuration

In this step, user needs to provide necessary information about the target system, which includes flash bit width, flash start address, RAM start address, XTAL and TCK.

Bit-Width and Chip Number

Some external flash chips can operate at different bit-widths, for example 8-Bit, 16-Bit and 32-Bit. Normally, drivers for different bit-widths are different. Hence, user needs to specify the bit-width for this kind of chips. For chips support only one bit-width, the default one is used and user doesn't need to specify it. In some design, multiple chips are used. In this case, user also needs to specify the right chip number.

Flash Start Address

To operate on the target flash, H-Flasher needs to know the flash start address. So, user needs to specify the start address of the flash. To H-Flasher, the valid address space is from (Flash Start Address) to (Flash Start Address + Size - 1). Any address out of this range is treated as illegal. Generally, flash can be accessed by address 0x0 without initialization. But, some system supports remap and can map flash to different addresses. For this case, user needs to ensure that the specified flash start address is consistent to the provided init scripts. In a word, please provide the init scripts when necessary and make sure that H-Flasher can access flash on the specified address.

RAM Start Address

User needs to designate a RAM space, which should be $\geq 4\text{K Bytes}$, because H-Flasher requires a 4K Bytes RAM space for driver use. The valid address range is from (RAM Start Address) to (RAM Start Address + 4K - 1). H-Flasher downloads the flash driver into this area. The flash driver can be downloaded into both SRAM and SDRAM. If the target system has on-chip SRAM, it is suggested to use on-chip SRAM instead of external SDRAM. The reason is that the access of SRAM is much faster than that of SDRAM. Meanwhile, please provide necessary init scripts for the initialization of memory system and ensure that the designated RAM space is accessible.

XTAL

For some chips, H-Flasher needs to know the frequency of the external crystal oscillator. H-Flasher uses this for the configuration of system clock. When the flash chip is specified, the input for XTAL may be disabled or enabled accordingly. When it is enabled, please specify the XTAL. Otherwise, ignore it.

INIT TCK & PGM TCK

INIT TCK specifies the TCK speed used during the initialization stage and the PGM TCK specifies the TCK speed used during the actual programming stage. Normally, the target system can support higher TCK speed after appropriate initialization. Hence, user can specify a lower TCK speed for successful initialization and a higher TCK speed for better programming speed. Please note that INIT TCK and PGM TCK are active only when USB based H-JTAG emulator is in use.

5.2.3 Init Script

In this step, user needs to provide the init scripts for the initialization of target system. User can edit scripts in the editor comes with H-Flasher. For more information on the definition of scripts, please refer to Chapter 6.

For on-chip flash, no init script is needed, because the driver already includes it. For external flash, init scripts are necessary. The purpose of init scripts is to configure the system clock and memory system. The later one is more important because correct initialization of memory system is the prerequisite. Otherwise, H-Flasher can't access flash and SDRAM.

If H-Flasher can't download driver to RAM, it notifies user with error message: Can't download driver to specified address. Most of the time, the cause is no init script is provided or the init script is not correct. To provide right scripts, user needs to have good understanding on the target system. Hence, user is suggested to read the datasheet carefully, especially the memory configuration.

Tip:

When USB based H-JTAG emulator is used, user is suggest to configure the system clock through init scripts to gain better performance.

5.2.4 Programming

In this step, user can perform operations on flash. The supported operations include check flash and target information, program flash, verify flash, erase flash and check whether the flash is empty.

- **Reset**

The reset operation can be used to perform system reset on target.

- **Check**

The check operation reads the flash ID and other basic target information. User can use this operation to test whether the configuration is correct or not.

- **UnProtect**

This operation can be used to un-protect a protected flash chip. When the selected flash is not supported by this operation, the button will be disabled automatically. Currently, the STM32F series are supported.

- **Program**

H-Flasher provides three types of programming, Auto Flash Download, Intel HEX Format and Plain Binary Format for different scenarios. For flash programming, both the data to be written and the destination address are indispensable. The difference among these three types is where the information comes from.

- A - Auto Flash Download**

- For Auto Flash Download, no source file and destination address are needed to be specified. All the information is from H-Jtag.

- B - Intel HEX Format**

- HEX file includes both the data/program and address information. Hence, user only needs to specify the source file when Intel HEX format is selected. H-Flasher extracts the address from HEX file automatically and uses it as the destination address.

- C - Plain Binary Format**

- Plain binary file includes only the program/data. For plain binary format, user needs to specify both the source file and the destination address

- **Verify**

This operation can be used to verify the programming by reading the content of target flash and comparing it with the source file.

- **Erase & Check Blank**

The erase and check blank operations can be used to erase the flash or check whether the flash is empty. For both operations, user can specify the range using the list boxes.

- **Read**

The read operation is provided to dump the content of memory on specified address. To read the content of memory, please specify both the start address and size in terms of bytes for Nor Flash and On-Chip Flash, or specify the starting sector, starting page, ending sector and ending page for Nand Flash.

5.2.5 Program Options

H-Flasher provides some useful operation options, for example, reset target after programming, additional verification and encryptions. User can choose these options on demand.

RESET

When enabled, H-Flasher will reset the target when the programming is done.

VERIFICATION

When enabled, H-Flasher will read the data from flash and compare them with the source file for the second time, when the programming is done.

SKIP ID CHECK

When enabled, H-Flasher will skip the check of flash ID during the operations.

ERASE CHIP

When enabled, H-Flasher will erase the entire flash chip instead of those affected sector before perform the flash programming.

SMART MODE

When enabled, H-Flasher will backup the content of the flash before programming and then restore them during the programming. This option can ensure the data which are not covered by the source file keep unchanged.

NXP LPC1700/2000

This option determines if H-Flasher adjusts the checksum of the vector table before the programming.

ATMEL AT91SAM

When enabled, H-Flasher will set the security bit to enable flash protection when the programming is done.

ST STM32F

When enabled, H-Flasher will set the RDP option byte to enable flash protection when the programming is done.

NAND FLASH PGM OPTIONS

To program NAND flash, user needs to provide the following information to H-Flasher.

- ✓ Programming Mode:
Specify how to program the NAND flash, skip bad blocks or relocate bad blocks;
- ✓ Scan of Bad Blocks:
Specify how to scan the bad blocks for relocation mode, erase the entire chip or only erase the affected blocks, reserved area for relocation and reserved blocks for relocation;
- ✓ Reserved Area for Relocation:
Specify the reserved blocks for relocation;

-
- ✓ **Reserved Area for User Table:**
Specify the reserved area for bad block table, relocation table or user data;

H-Flasher supports two NAND flash programming modes, skip mode and relocation mode. For the skip mode, H-Flasher will skip a bad block and jump to the next good one. For the relocate mode, H-Flasher will relocate a bad block to a good block in the specified reserved area. When skip mode is selected, H-Flasher will simply skip a bad block and program the data to the next good one in sequence. When the relocate mode is selected, H-Flasher will first scan the flash to collect the bad block information by erasing the entire chip, or only erasing the affected blocks, the reserved area for relocation and the reserved area for user tables. During the programming, if a bad block is encountered, H-Flasher will program the data to the first free good block in the reserved area for relocation. At the same, H-Flasher will record the relocation information. When the programming is done, H-Flasher will send the bad block table and relocation table information to the NAND flash driver. In the flash driver, a function named `nand_info_table()` will accept all the information sent by H-Flasher. User can modify this function to build the bad block table and relocation table in the reserved area for user table as required.

 **Note-1:**

In skip mode, H-Flasher will not send the bad block table and relocation table information to the NAND flash driver when the programming is done.

 **Note-2:**

Due to the characteristic of NAND flash, it is not possible to provide a common flash driver which fits all hardware platforms. When the bad block table or relocation table are needed, user should modify the `nand_info_table()` function in the flash driver based on user's own requirements.

 **Note-3:**

Some options only work under normal operation mode. For auto flash download mode, H-Flasher ignores all these options.

 **PRODUCTION MODE**

When this option is enabled, H-Flasher enters production mode. In production mode, the software operations are simplified to improve the efficiency. After entering production mode, H-Flasher keeps detecting target. When a target is detected, H-Flasher starts the flash programming process automatically. When the programming is done, user is notified to disconnect the target and connect the next one. So, the only thing user needs to do is connect a target and disconnect it when the programming is done, and then connect the next one.

5.3 Useful Tips

 **Tip-1:**

H-Flasher and Flasher Lite are same, except that H-Flasher Lite does not support Auto Flash Download. To use Auto Flash Download, please run and configure H-Flasher instead of H-Flasher Lite.

 **Tip-2:**

During the configuration, if any edit box or list box is in gray, it means that only one option is available. User doesn't need to specify.

 **Tip-3:**

In H-Flasher, the entire configuration can be saved as HFC file for later use.

 **Tip-4:**

Before starting the programming, H-Flasher will erase certain part of the flash automatically. Hence, user doesn't need to erase the flash manually.

 **Tip-5:**

The erase operation is sector based. To avoid the loss of data, H-Flasher provides auto backup and restore mechanism. H-Flasher will backup some data before erase and restore them during the programming. With this mechanism, the contents of the flash are kept unchanged except those covered by current programming.

 **Tip-6:**

When user sees the error message "Destination flash address is out of range", it means that the specified destination address or the destination address extracted from HEX file is not inside the valid flash address range. Please check the destination address and ensure it is valid.

 **Tip-7:**

For some chip, the ID might be changed after some new version is released. In this case, please contact us. We will provide updated flash driver.

 **Tip-8:**

If something goes wrong during the operation, please check the configuration and ensure that correct configuration is provided. If the error still occurs when correct configuration is provided, please contact us. We will analyze where the problem is and provide updated flash driver when necessary.

5.4 Example 1 – AT91SAM7X256

AT91SAM7X256 is an ARM7 based chip from ATMEL. This chip comes with 256K Bytes internal flash and 64K Bytes internal SRAM. This section shows how to configure and program it with H-Flasher.

5.4.1 Flash Selection

In this step, select AT91SAM7X256 as the target flash, as shown in Fig 5-2.

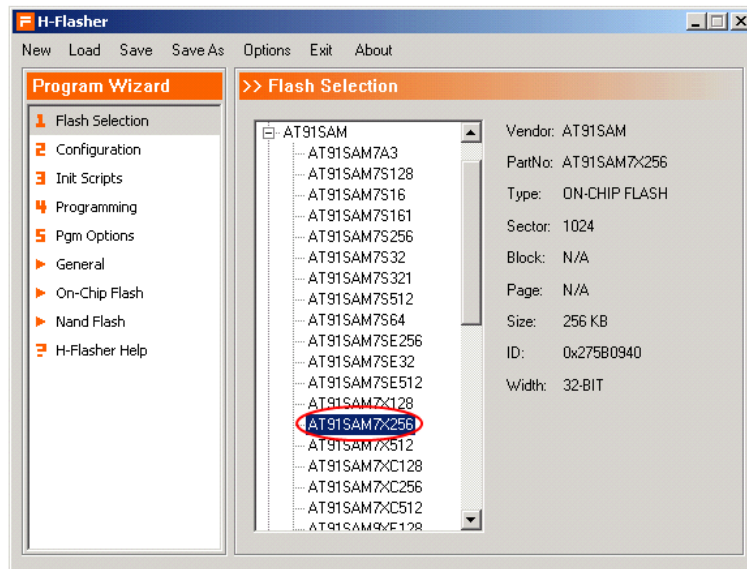


Fig 5-2 Flash Selection: AT91SAM7X256

5.4.2 Configuration

In this step, user needs to provide some basic memory information. For AT91SAM7X256, the bit-width, flash start address and RAM start address are all fixed. Default configuration is used. In this example, no XTAL needs to be specified.

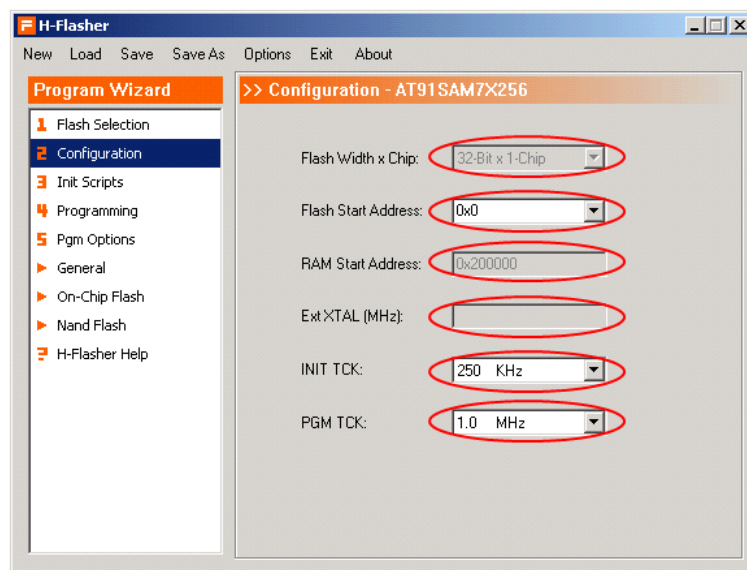


Fig 5-3 Configuration: AT91SAM7X256

5.4.3 Init Script

In this third step, user needs to provide the init script. For AT91SAM7X256, the driver already includes the initialization. Hence, user doesn't need to provide init script for AT91SAM7X256. In this case, the edit buttons are all disabled automatically, as shown in Fig 5-4.

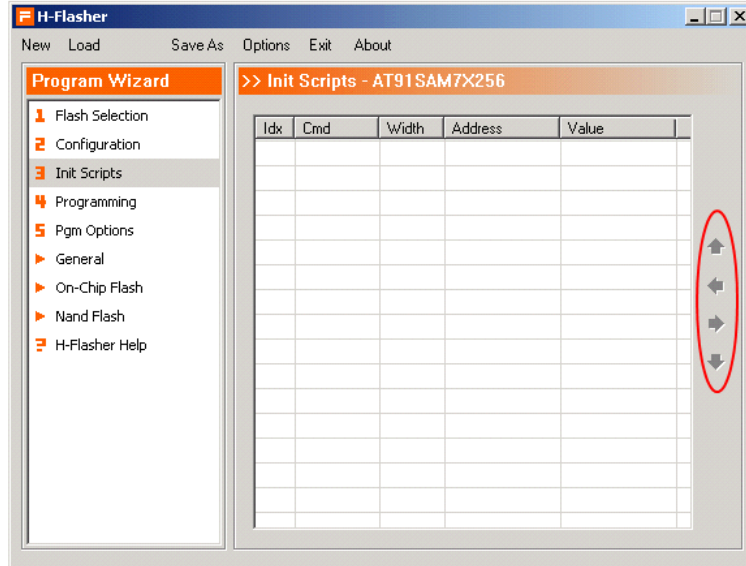


Fig 5-4 Init Script: AT91SAM7X256

5.4.4 Program Options

Before starting the operation, user can choose different program options as required. In this example, we choose to perform the additional verification and reset target when the programming is done.

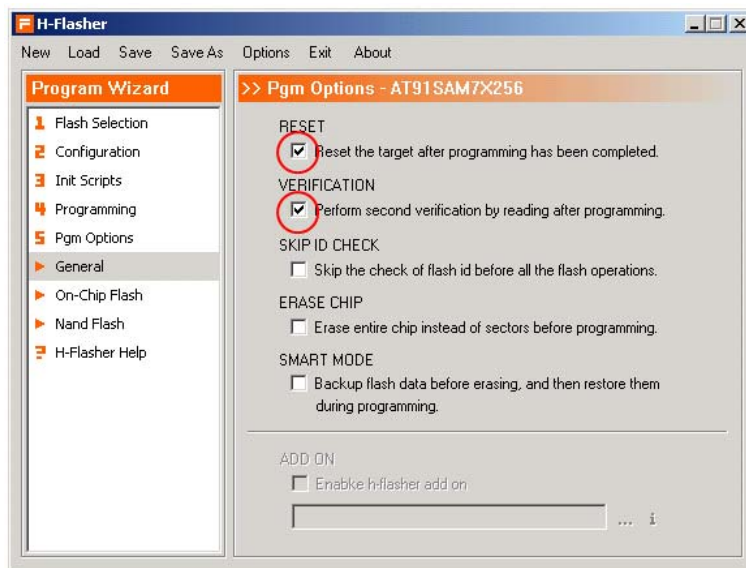


Fig 5-5 Program Options

5.4.5 Programming

After the configuration is completed in the first 4 steps, user can operate on flash in this step. First, let's try to check the target information by click "Check". In this example, the check result is shown in Fig 5-6. The result indicates that the configuration works well.

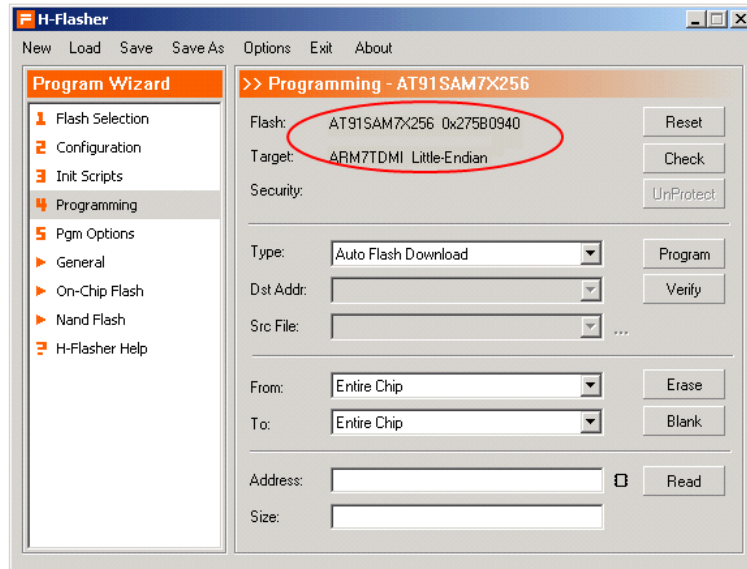


Fig 5-6 Check Result: AT91SAM7X256

Next, let's try to program a binary file. In this example, the settings are shown in Fig 5-7. Plain binary format is selected, the source file is TEST.bin located under C:\ and the destination address is 0x0 (Flash base address).

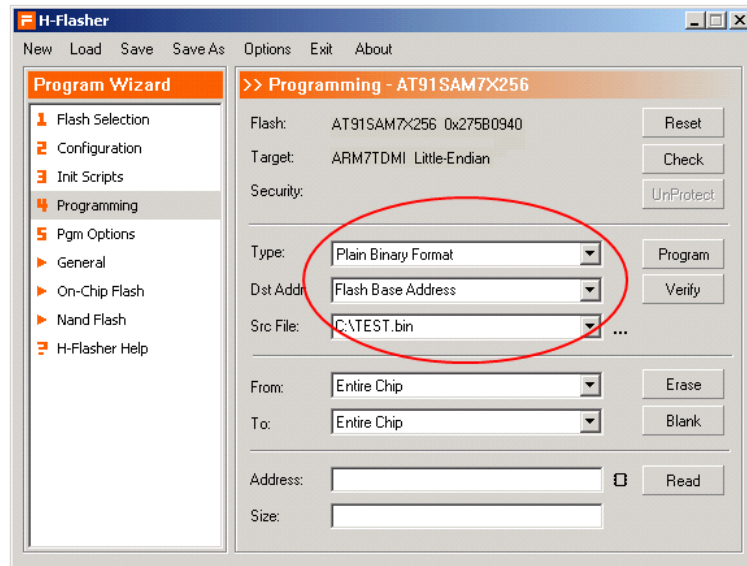


Fig 5-7 Programming Settings

Then, click "Program" to start the programming. During the process, user can see the progress, average speed and used time. When the programming is completed successfully, H-Flasher notifies user with a message, as shown in Fig 5-8.

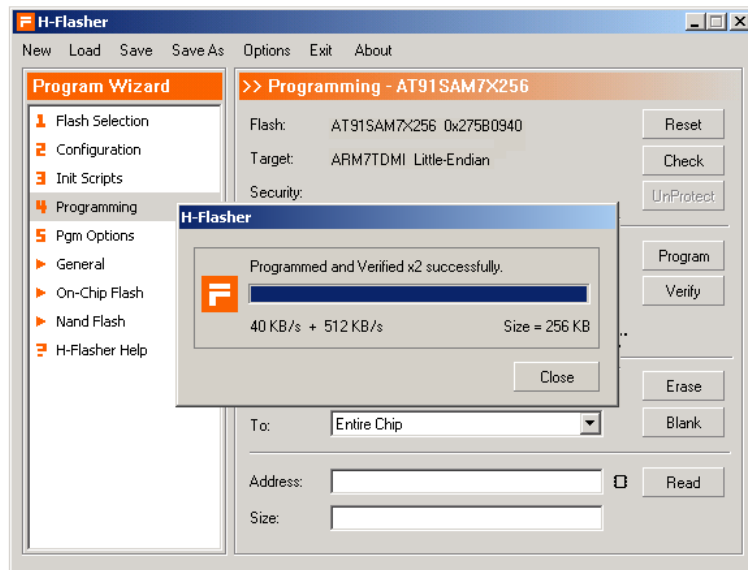


Fig 5-8 Programming Is Completed

5.4.6 Save Configuration

User can save the above configuration as a HFC file. Later, user can load the HFC file in H-Flasher directly and need not to configure again.

5.5 Example 2 – LPC2210 + SST39VF1601

LPC2210 is an ARM7 based chip from NXP (Former PHILIPS Semiconduct). This chip is equipped with 16K Bytes internal SRAM, but without internal flash. This chip has four external memory banks, which can be used to expand external flash and SDRAM. In this example, it is assumed that BANK0 is used for external flash (SST39VF1601). The address range is 0x80000000 to 0x80FFFFFF. BANK1 is used for external SDRAM and the address range is 0x81000000 to 0x81FFFFFF. Next, we are going to introduce how to program H-Flasher + SST39VF1601 with H-Flasher.

5.5.1 Flash Selection

In the first step, as indicated, select target flash. In this example, SST39VF1601 should be selected. The selection is shown in Fig 5-9.

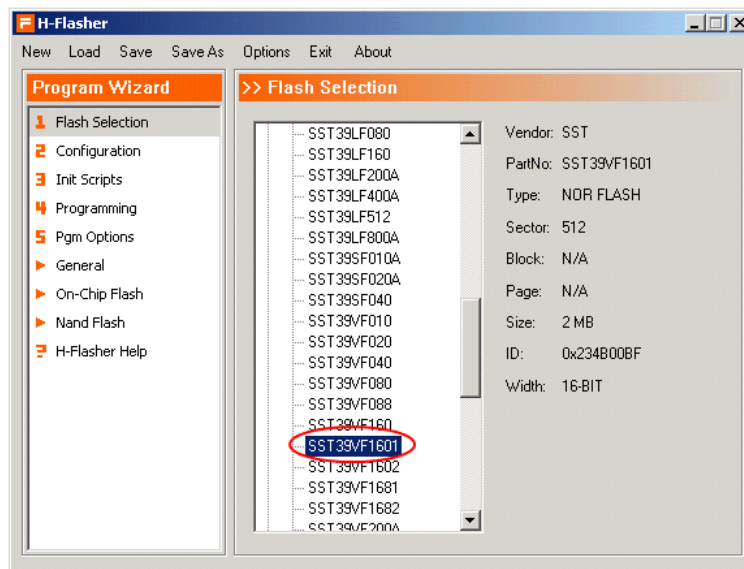


Fig 5-9 Flash Selection: SST39VF1601

5.5.2 Configuration

In this step, we need to provide the information on memory system. SST39VF1601 supports only 16-Bit mode. So, we can use the default bit-width. SST39VF1601 is expanded via BANK0, so that the flash start address is 0x80000000. Although LPC2210 has internal SRAM, we use external SDRAM in this example for illustration. The external SDRAM is expanded via BANK1. Hence, the RAM start address is 0x81000000. Actually, we can specify any 4K space within the SDRAM range. The XTAL also doesn't need to be specified. In this example, the final settings are shown in Fig 5-10.

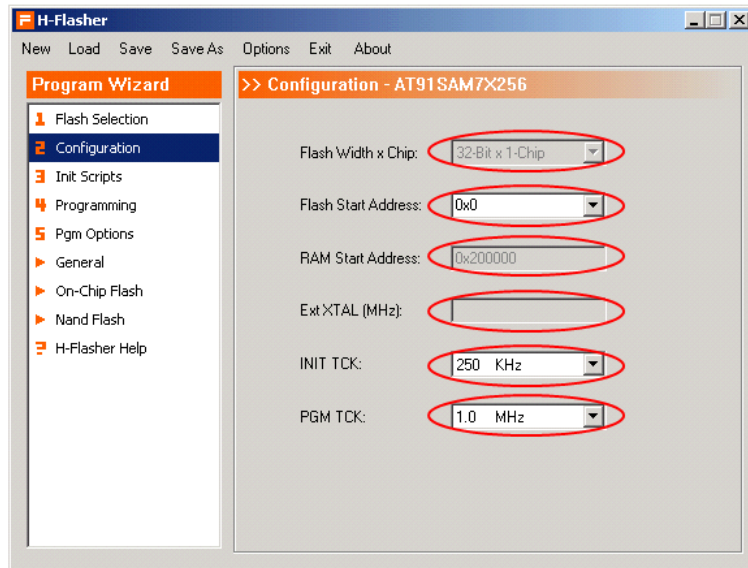


Fig 5-10 Configuration: LPC2210 + SST39VF1601

5.5.3 Init Script

According to the datasheet of LPC2210, we need to configure three registers: PINSEL2@0xE002C014, BCFG0@0xFFE00000, and BCFG1@0xFFE00004. PINSEL2 is a pin selection register, which is used to configure some multiplexed pins. BCFGx is bank configuration register, which is used to set the bus width and read/write wait cycles. For details, please refer the datasheet. In this example we need three scripts listed in Fig 4-10 to make sure that the flash and SDRAM are accessible.

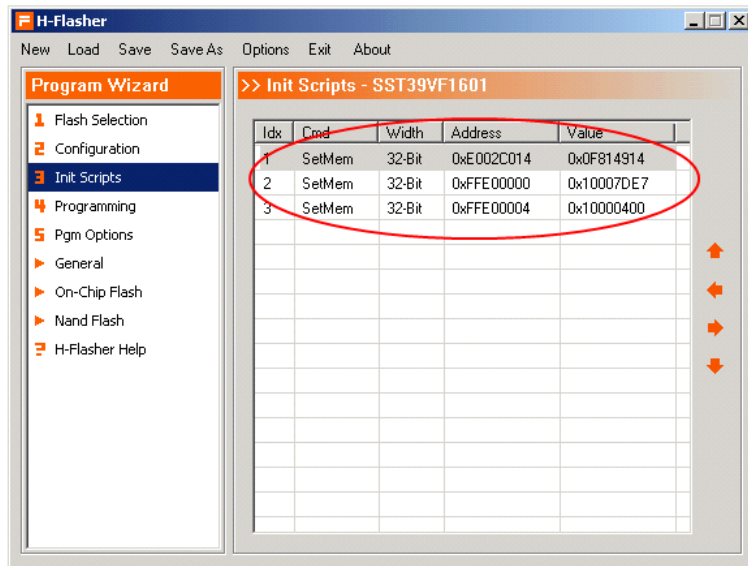


Fig 5-11 Init Script: LPC2210 + SST39VF1601

5.5.4 Program Options

Before starting the operation, user can choose different program options as required. In this example, we choose to perform the additional verification and reset target when the programming is done.

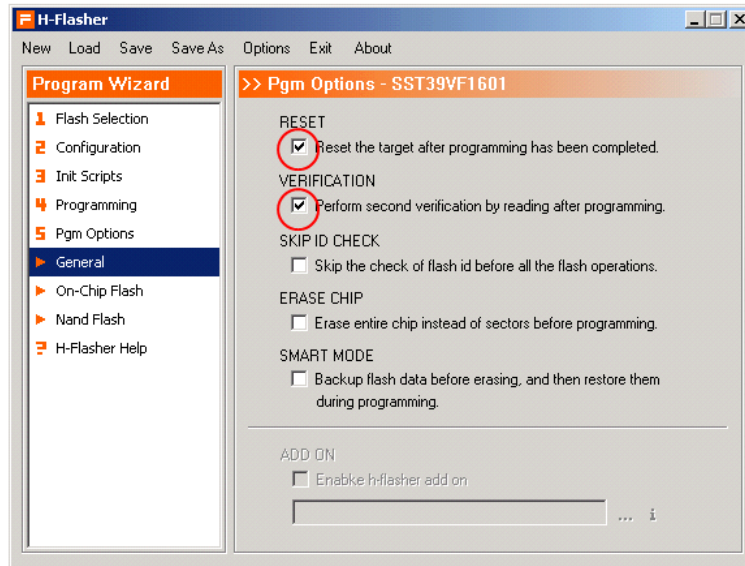


Fig 5-12 Program Options

5.5.5 Programming

After the configuration is done, we can operate on target flash in the fourth step of the wizard. First, let's try to check the target information by clicking "Check". In this example, the check result is shown in Fig 5-13. The result indicates that the configuration is correct.

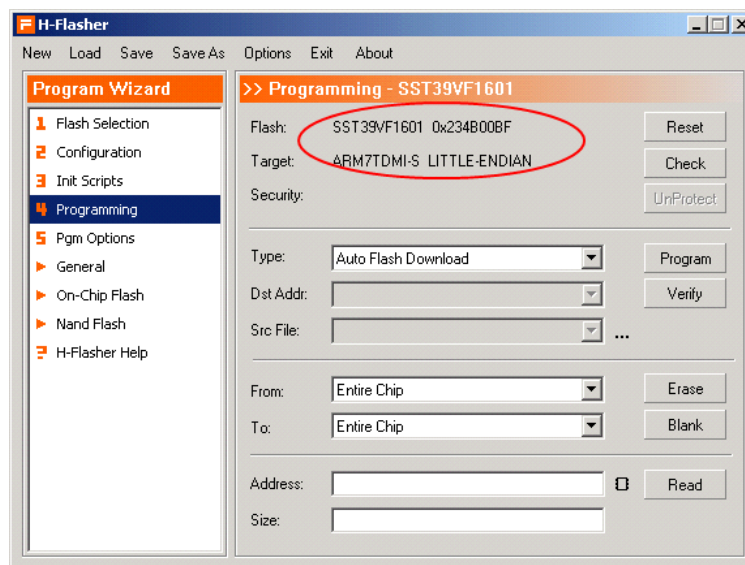


Fig 5-13 Check Result: LPC2210 + SST39VF1601

Next, let's try to program a binary file. In this example, the settings are shown in Fig 5-14. Plain binary format is selected, the source file is TEST.bin located under C:\ and the destination address is 0x80000000.

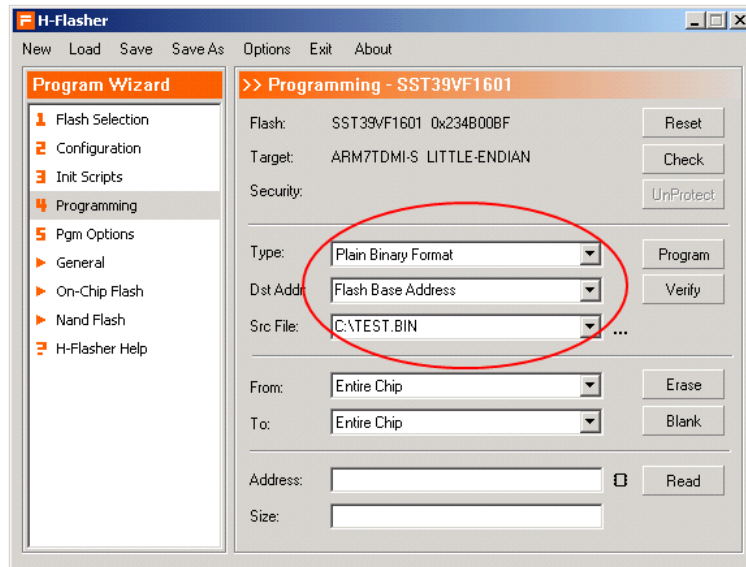


Fig 5-14 Programming Settings

Then, click “Program” to start the programming. During the process, user can see the progress, average speed and used time. When the programming is completed successfully, H-Flasher notifies user with a message, as shown in Fig 5-15.

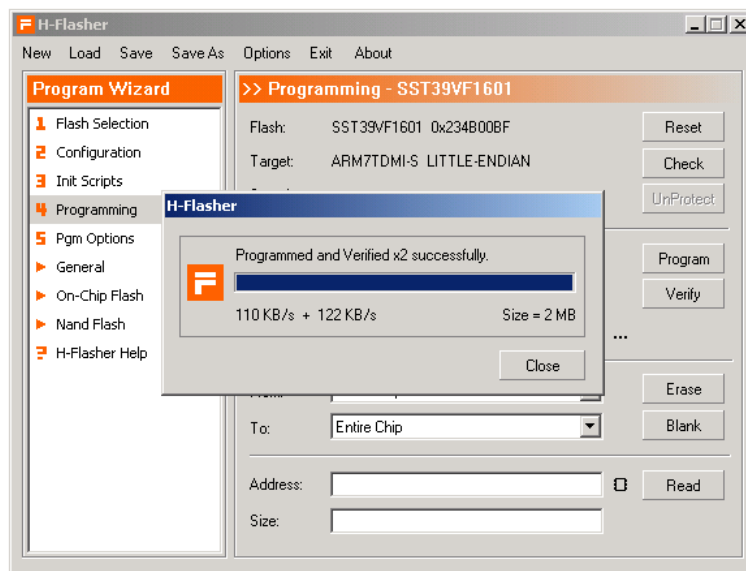


Fig 5-15 Programming Is Completed

5.5.6 Save Configuration

As shown in previous example, user can also save the above configuration as a HFC file for future use.

Chapter 6 Initialization Script

This chapter introduces the definition of initialization scripts and how to edit scripts in H-Jtag and H-Flasher.

6.1 Definition of Script Commands

H-Jtag defines 6 script commands, *Setmem*, *Getmem*, *Delay*, *SysReset*, *SoftReset* and *SetPPMR*. The purpose of each script command is listed in Table 6-1. These 5 script commands can be combined to initialize different systems.

Table 6-1 Script Commands

Command	Function
<i>Setmem</i>	Set memory value
<i>Getmem</i>	Read memory value
<i>Delay</i>	Add delay
<i>SysReset</i>	Perform system reset
<i>SoftReset</i>	Perform soft reset
<i>SetPPMR</i>	Set CP15 Peripheral Port Memory Remap Register for ARM11

Note:

Currently, only 6 script commands are defined. But these commands can satisfy most situations. In the future, the command set may be extended to accommodate new requirements.

6.1.1 Setmem

Setmem is the most important script command. This command can be used to set the value of memory, which includes memory mapped registers. The format of this script command is

Setmem bit-width dest-address value

- *Setmem* – Command;
- *Bit-Width* – Bit width of the write operation, which could be 8-bit, 16-bit or 32-bit;
- *Dest-Address* – Destination address of the write operation. Please ensure that the address is aligned;
- *Value* – The value written to the destination address;

Examples:

Setmem 08-Bit 0x0 0x12 – Write 0x12 to 0x0, bit width is 8-bit

Setmem 16-Bit 0x0 0x1234 – Write 0x1234 to 0x0, bit width is 16-bit

Setmem 32-Bit 0x0 0x12345678 – Write 0x12345678 to 0x0, bit width is 32-bit

6.1.2 Setmem

This command can be used to read the value of a specific memory address. The format of this script command is

Getmem bit-width dest-address

- *Getmem* – Command;
- *Bit-Width* – Bit width of the read operation, which could be 8-bit, 16-bit or 32-bit;
- *Dest-Address* – Destination address of the read operation. Please ensure that the address is aligned;

Examples:

Getmem 08-Bit 0x0 – Read the value at address 0x0, bit width is 8-bit

Getmem 16-Bit 0x0 –Read the value at address 0x0, bit width is 16-bit

Getmem 32-Bit 0x0 –Read the value at address 0x0, bit width is 32-bit

6.1.3 Delay

Delay command is used to add certain delay between two scripts. Some operation needs some time before it takes affect. This command can be used as null operation to wait previous script gets completed. The format of this script command is

Delay time (millisecond)

- *Delay* – Command;
- *Time* – Delay time in millisecond;

Examples:

Delay 100 – *Delay 100 milliseconds;*

Delay 5000 – *Delay 5000 milliseconds;*

6.1.4 SysReset

SysReset command is used to perform system reset. This command can only be used as the first command in user's scripts. If *SysReset* appears in other position, it will be ignored.

Note: *SysReset* command can only be used as the first command in user's scripts.

The format of this script command is

SysReset (No parameter)

- *SysReset* – Command;

6.1.5 SoftReset

SoftReset command is used to perform soft reset. The main purpose is to reset CP15 control register. For target with CACHE and MMU, this command can be used to disable both the MMU and CACHE. For this kind of target, the program or OS inside the flash may configure the MMU and perform complicated remap operation. To re-program the target, it is suggested to disable the MMU and CACHE with *SoftReset*. By disabling the MMU and CACHE, it is easy to manage the memory map and make it same as what we expected. The format of this command is

SoftReset (No parameter)

- *SoftReset* – Command;

6.1.6 SetPPMR

SetPPMR command is used to set the CP15 Peripheral Port Memory Remap Register for ARM11. The format of this command is

SetPPMR Value

- *SetPPMR* – Command;
- *Value* – New value for PPMR register;

Example:

SetPPMR 0x70000013 – Set PPMR register to 0x70000013;

6.2 Edit Init Script

Both H-Jtag and H-Flasher provide script editor. The editors are shown in Fig 6-1 and Fig 6-2 respectively. Actually, the editors of H-Jtag and H-Flasher are same. The introduction in this section covers both.

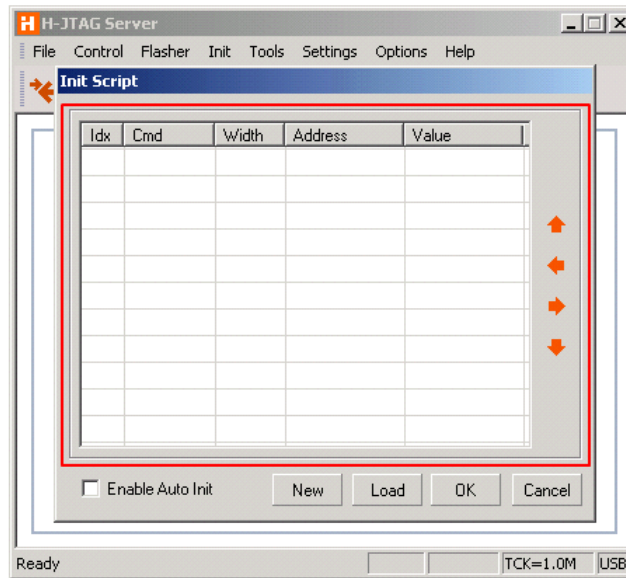


Fig 6-1 H-Jtag Script Editor

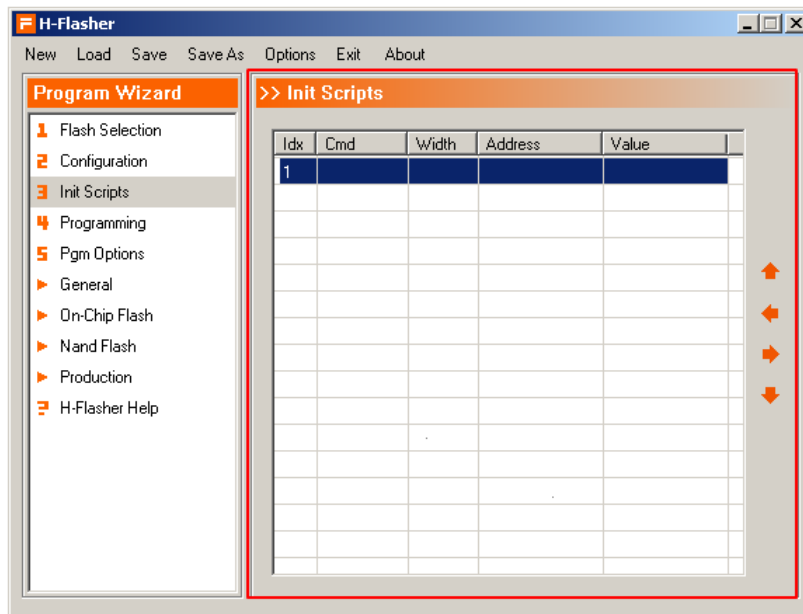










Fig 6-2 H-Flasher Script Editor

6.2.1 Edit Buttons

In the script editor, there are four buttons for editing. These four buttons are used to add, delete, move up or move down script. The detailed definitions are listed below.

-   Move up the selected script
-   Add a new script
-   Delete the selected script
-   Move down the selected script

6.2.2 Edit Script

For each new script, user first needs to select a command and then specify the parameters as defined. To add a new script, click “Add” on the right side. After a new script has been added, the editor looks like Fig 6-3.

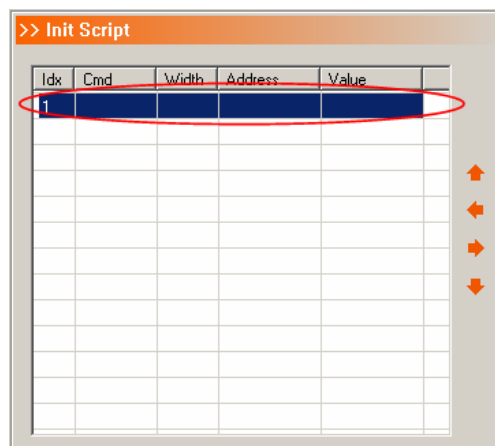


Fig 6-3 Add a New Script

A command list can be shown up by double clicking the Cmd column. The command list is shown in Fig 6-4. User can select a command from the list as needed.

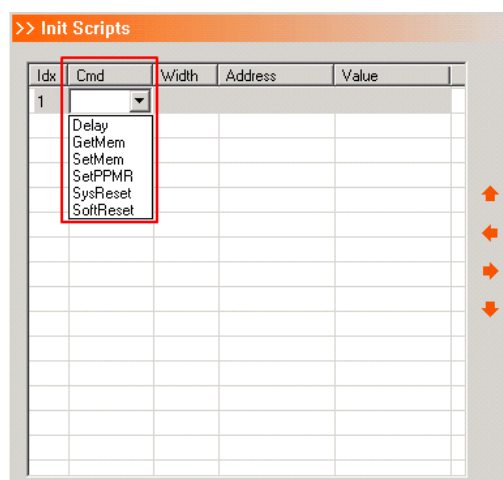
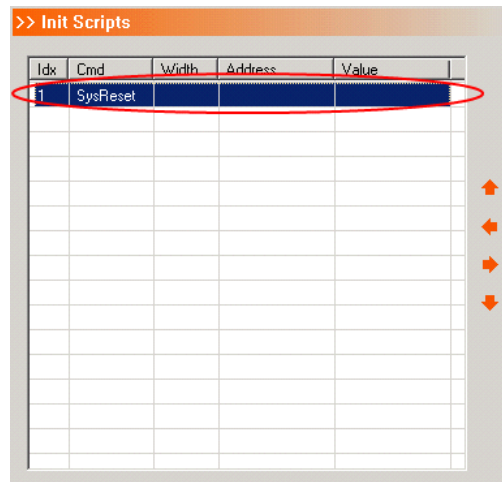


Fig 6-4 Command List

If *SysReset* is selected, no other parameter is needed. Fig 6-5 shows how the editor looks like after the completion of the *SysReset* script.

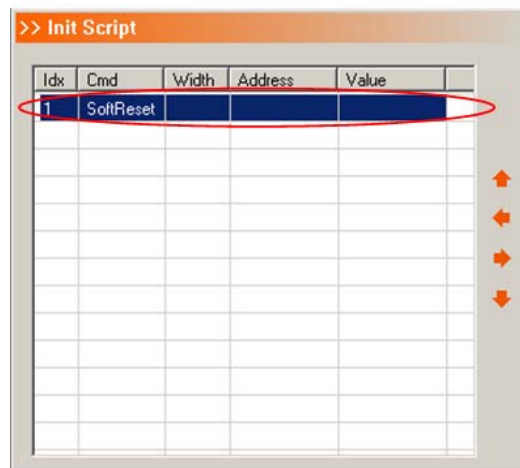


The screenshot shows a window titled '>> Init Scripts' containing a table with the following columns: Idx, Cmd, Width, Address, and Value. The first row is highlighted in blue and contains the value '1' in the Idx column and 'SysReset' in the Cmd column. A red oval highlights the first row. To the right of the table are four orange arrow icons pointing up, down, left, and right.

Idx	Cmd	Width	Address	Value
1	SysReset			

Fig 6-5 SysReset Script

If *SoftReset* is selected, no other parameter is needed. Fig 6-6 shows how the editor looks like after the completion of the *SoftReset* script.



The screenshot shows a window titled '>> Init Script' containing a table with the following columns: Idx, Cmd, Width, Address, and Value. The first row is highlighted in blue and contains the value '1' in the Idx column and 'SoftReset' in the Cmd column. A red oval highlights the first row. To the right of the table are four orange arrow icons pointing up, down, left, and right.

Idx	Cmd	Width	Address	Value
1	SoftReset			

Fig 6-6 SoftReset Script

If *Delay* command is selected, the delay value also needs to be specified. Fig 6-7 shows a script which delays 5000 milliseconds.

Idx	Cmd	Width	Address	Value
1	Delay			5000

Fig 6-7 Delay Script

If *Setmem* command is selected, all the bit-width, destination address and target value need to be specified. When *Setmem* command is selected, a bit-width list will be shown up by double clicking the Width column (Fig 6-8). User can select the right bit width from the list. Next, user needs to input the destination address and value in the Address column and Value column respectively. Fig 6-9 shows script *Setmem 32-Bit 0x0 0x12345678*, which is to write 0x12345678 to 0x0.

Idx	Cmd	Width	Address	Value
1	Setmem	<ul style="list-style-type: none"> 08-Bit 16-Bit 32-Bit 		

Fig 6-8 List of Bit-width

Idx	Cmd	Width	Address	Value
1	Setmem	32-Bit	0x00000000	0x12345678

Fig 6-9 Setmen Script

If *Getmem* command is selected, both the bit-width and destination address need to be specified. When *Getmem* command is selected, a bit-width list will be shown up by double clicking the Width column (Fig 6-10). User can select the right bit width from the list. Next, user needs to input the destination address in the Address column. Fig 6-11 shows script *Getmem 8-Bit 0x10000000*, which is to read the 8-bit value at address 0x10000000.

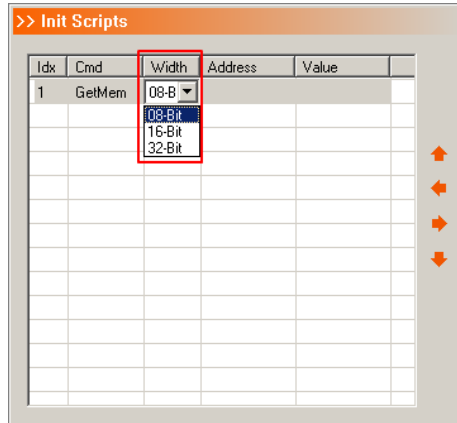


Fig 6-10 List of Bit-width

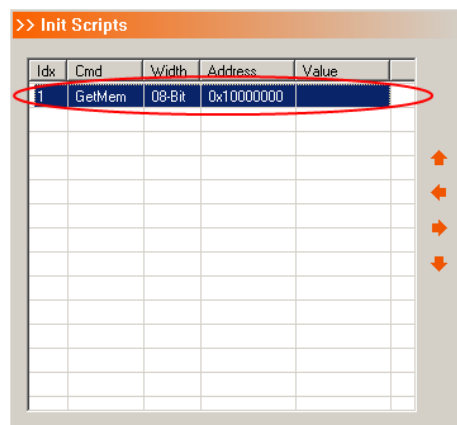
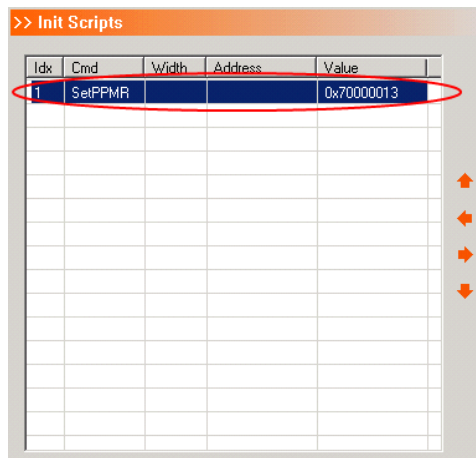


Fig 6-11 Getmen Script

If *SetPPMR* command is selected, the value for PPMR register also needs to be specified. Fig 6-12 shows a script which set PPMR register to 0x70000013.



6-12 SetPPMR Script

6.2.3 Add Script Comment

For each script command, user can add a comment. In the script editor, double click the index number before a command, a dialog will be popped up, as shown in Fig 6-13. User can review the existing comment or add a new one in the dialog.

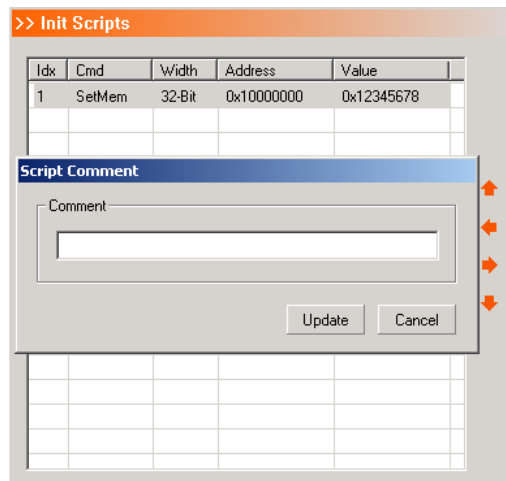


Fig 6-13 Script Comment

Chapter 7 Configure Debuggers

This chapter illustrates how to configure common debugger software, which include AXD, RVDS, IAR and KEIL. For details on how to use respective debuggers, please refer to their own user manuals.

7.1 Configure AXD

ADS (Arm Developer Suit) is the most widely used IDE from ARM Corp. AXD is the debugger comes with ADS. This section introduces how to configure AXD and use it with H-Jtag.

First, start AXD and click Options -> Configure Target, as shown in Fig 7-1.

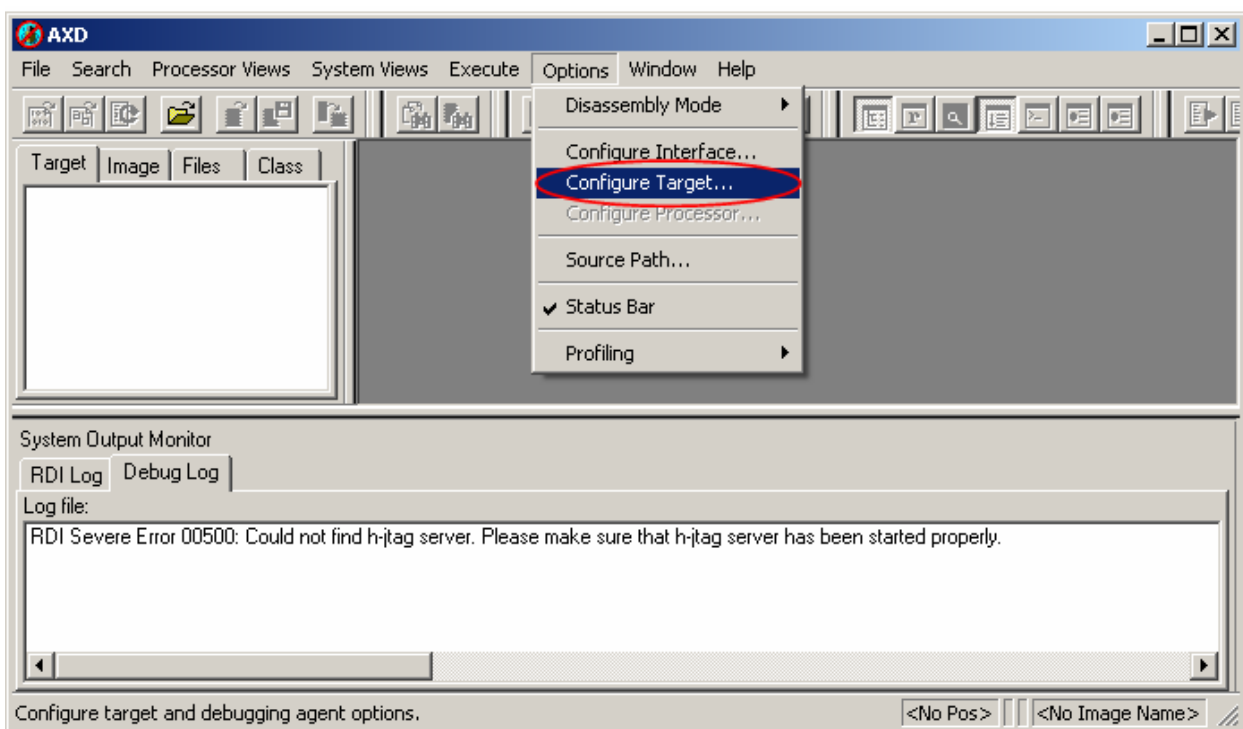


Fig 7-1 Configure Target Menu

Next, the choose target dialog (Fig 7-2) is popped up.

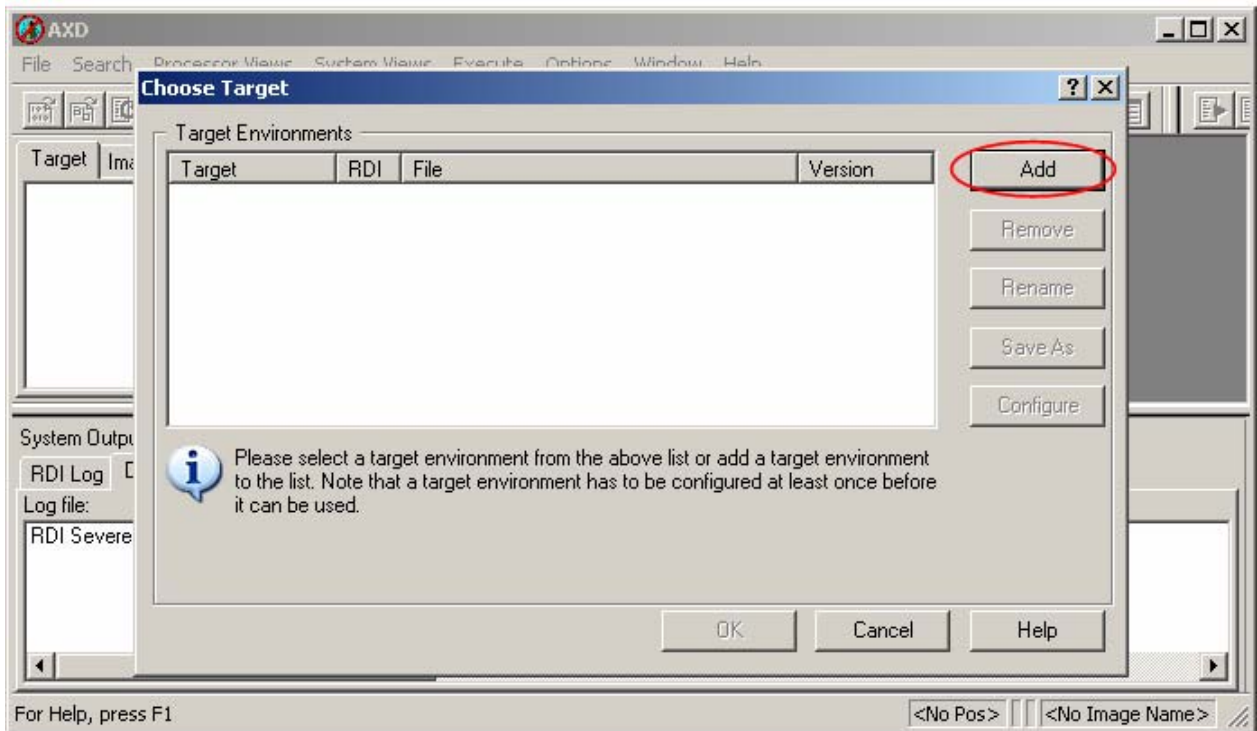


Fig 7-2 Choose Target Dialog

In the above figure, click “Add”, an open dialog (Fig 7-3) is popped up. In this dialog, please choose H-JTAG.DLL, which is located under the folder where H-Jtag is installed. Then click “Open”.

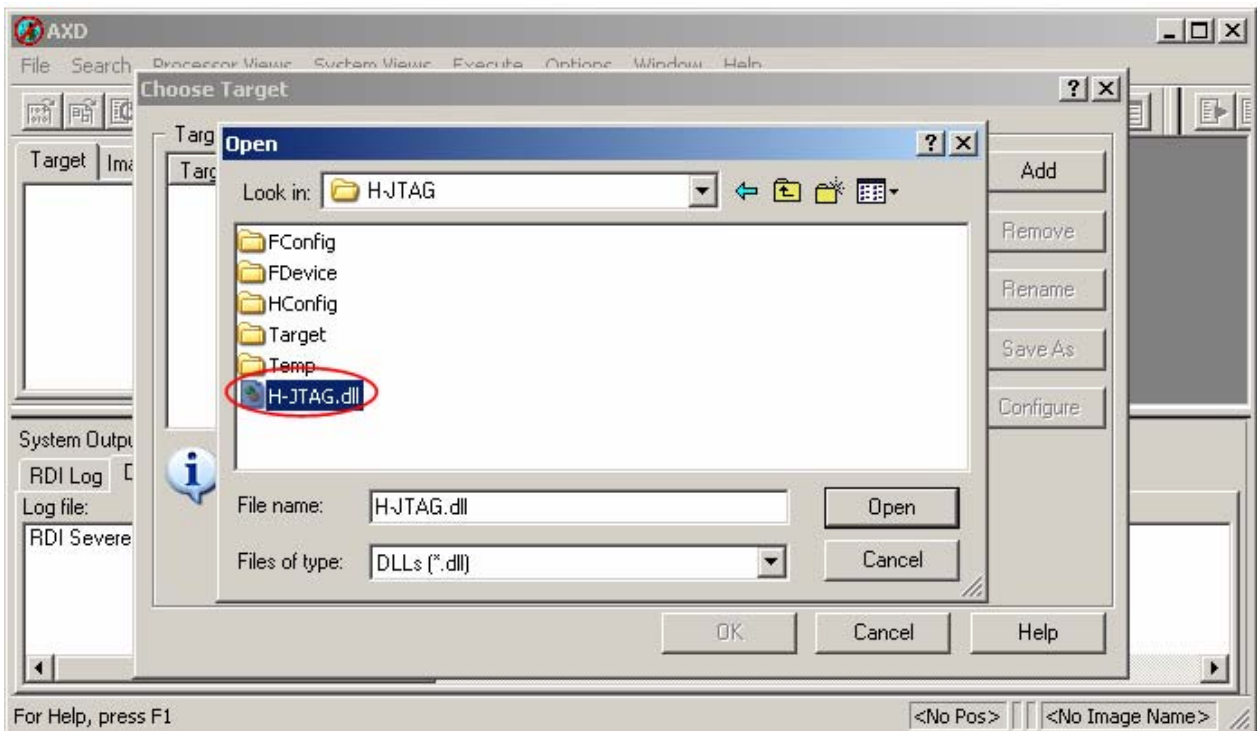


Fig 7-3 Choose H-JTAG.DLL

After H-JTAG.DLL is selected, user can find that H-JTAG.DLL has been added, as shown in Fig 7-4. In this step, user can check the basic information about H-Jtag by clicking “Configure” or double clicking H-JTAG. The basic information is shown in Fig 7-5. To complete the configuration, please click “OK” in Fig 7-4.

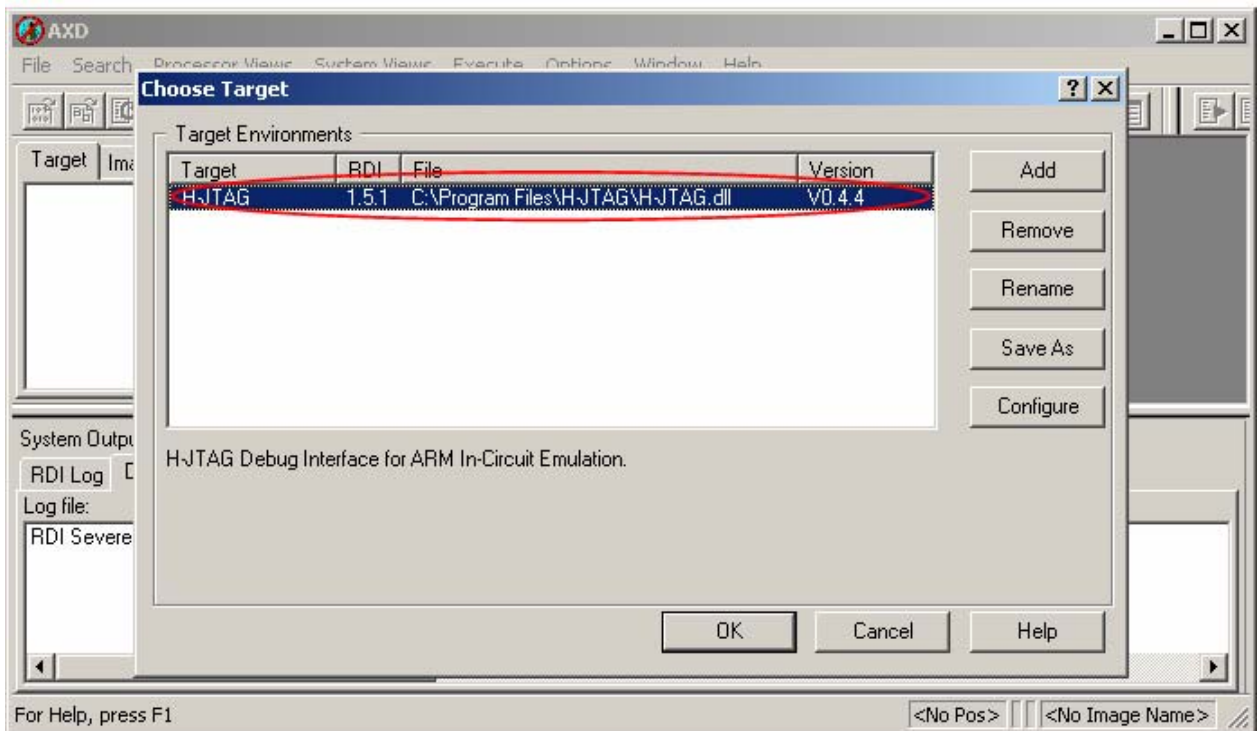


Fig 7-4 AXD Configuration

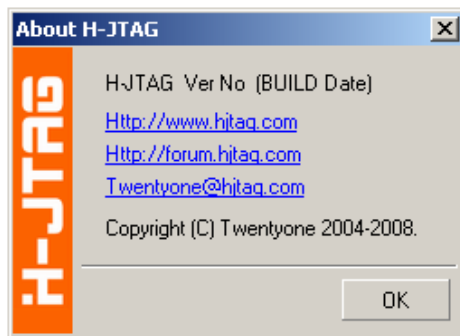


Fig 7-5 H-Jtag Information

7.2 Configure RVDS

RVDS stands for Realview Developer Suit, which is from ARM Corp. This section introduces how to configure RVDS to use with H-Jtag. The introduction is based on RVDS2.0, but the configuration for other versions is similar.

First start RVDS and then click “Click to Connect to a Target”, as shown in Fig 7-6.

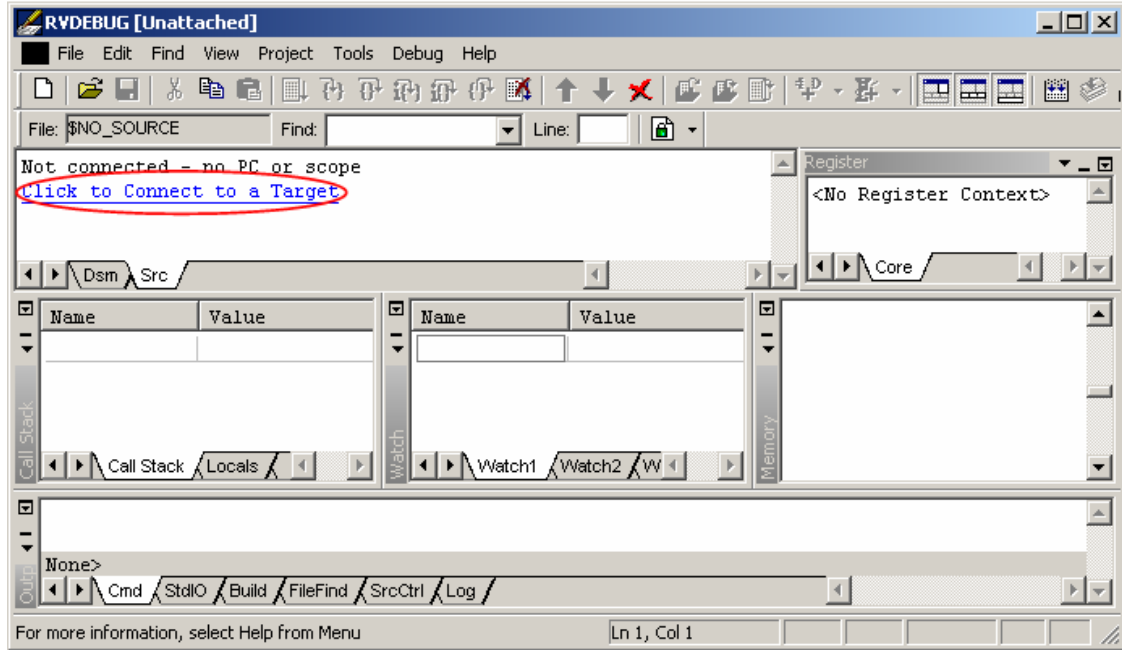


Fig 7-6 RVDS Main Window

Next, the connection control dialog is popped up (Fig 7-7).

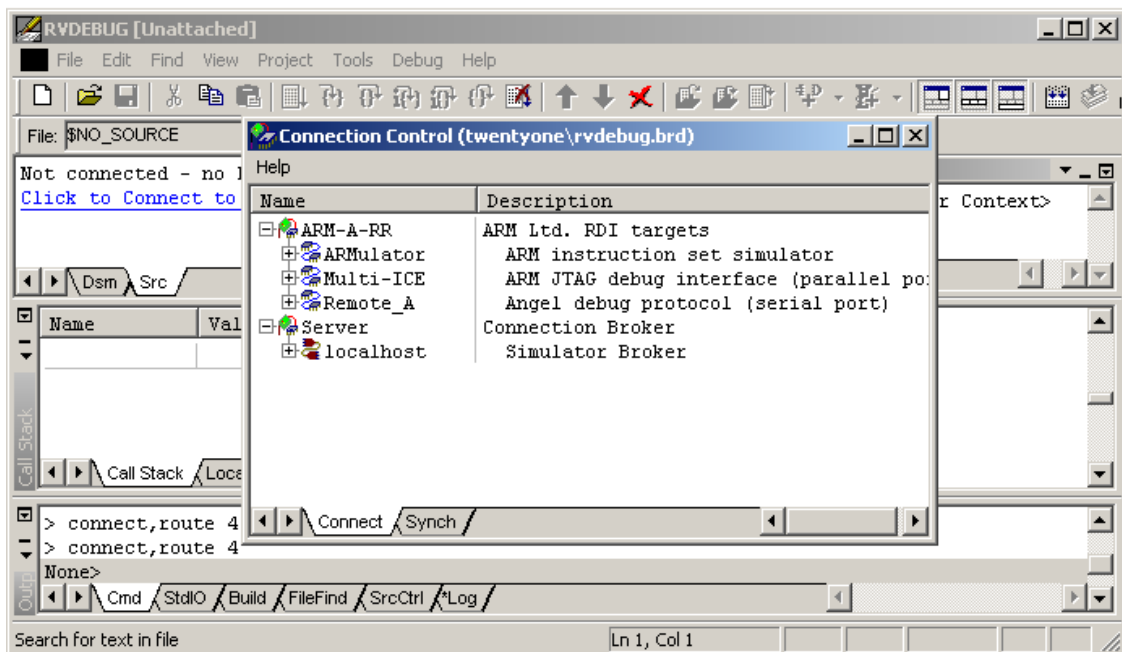


Fig 7-7 Connection Control Dialog

In Fig 7-7, right click inside the dialog to pop up the context menu (shown in Fig 7-8).

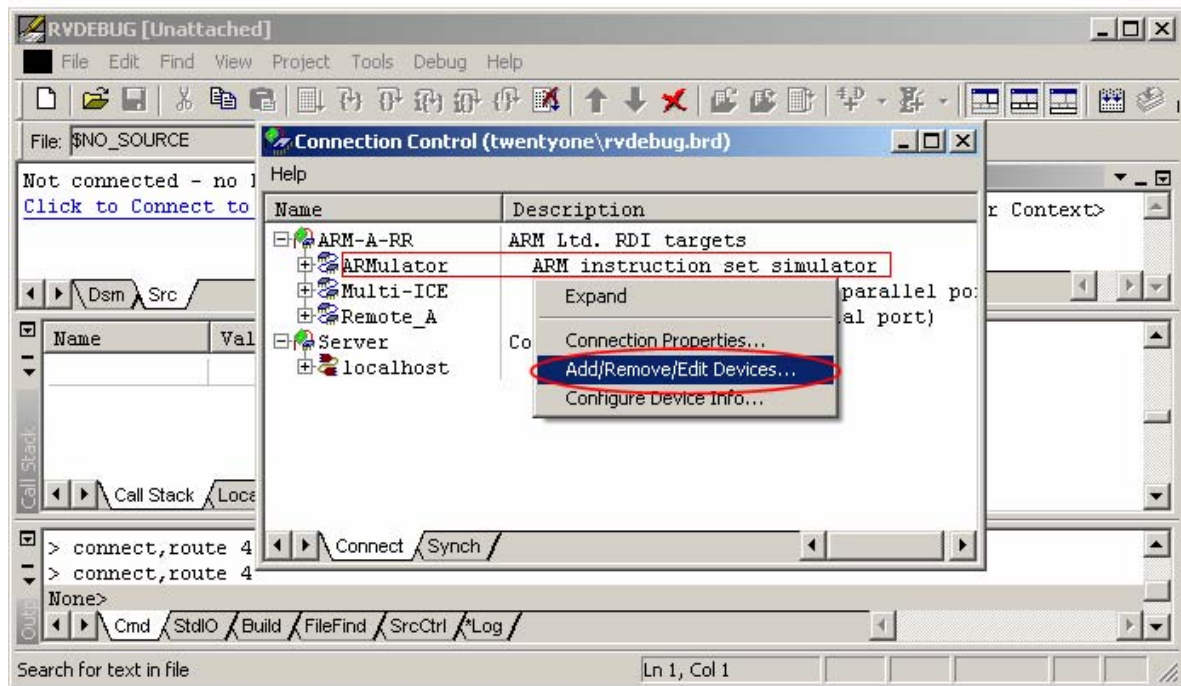


Fig 7-8 Context Menu

In the menu shown in Fig 7-8, click “Add/Revmove/Edit Devices”, the RDI Target List dialog is popped up. The dialog is shown in following figure.

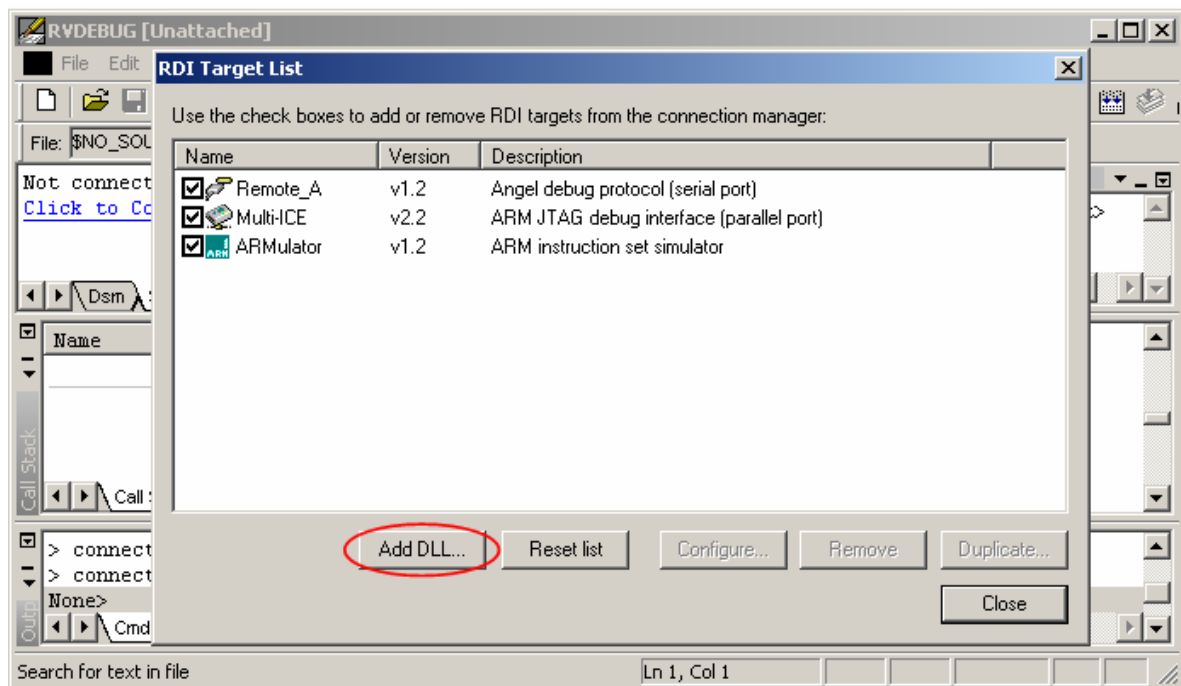


Fig 7-9 RDI Target List Dialog

In Fig 7-9, click “Add DLL”, the Select RDI DLL dialog is popped up. The Select RDI DLL dialog is shown below. In this dialog, choose H-JTAG.DLL located under the installation folder of H-Jtag. Then click “Open”.

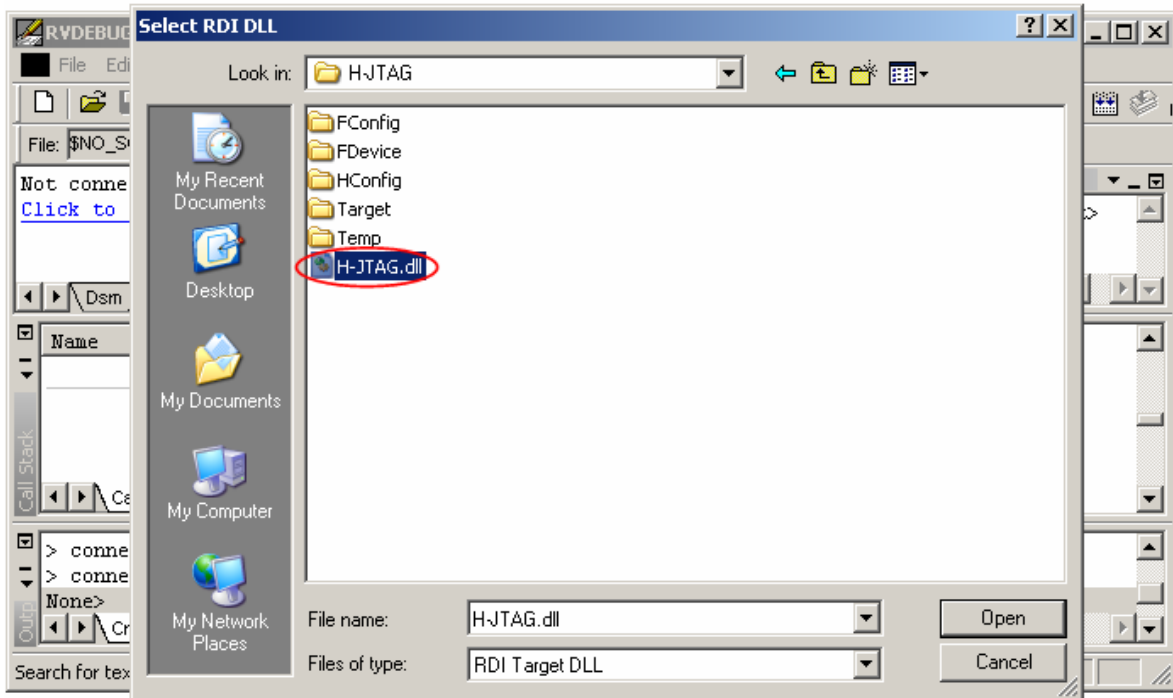


图 7-10 选择 H-JTAG.DLL

After H-JTAG.DLL is selected, a new dialog (Fig 7-11) is popped up. The new dialog is used to create a new RDI target. In this dialog, user can input a short name and a brief description or use the default ones.

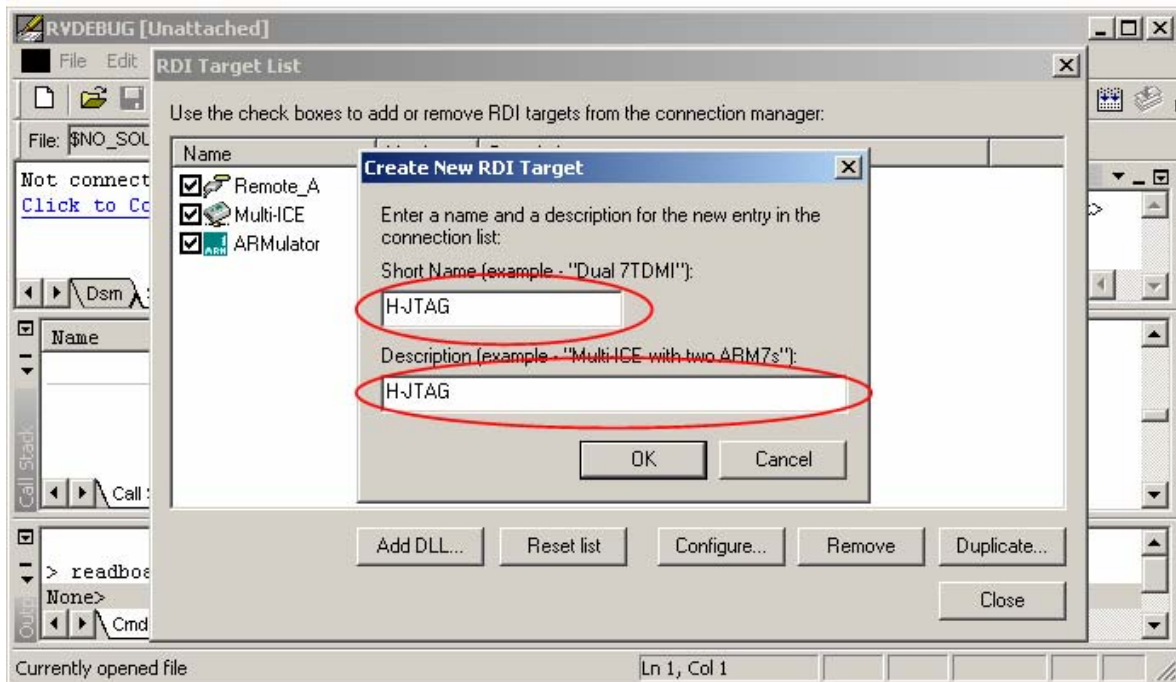


Fig 7-11 Create New RDI Target Dialog

After that, user can find that H-Jtag has been added into RVDS as shown in Fig 7-12. In this step, user can check the basic information about H-Jtag by clicking “Configure” or double clicking H-JTAG. The basic information is shown in Fig 7-13. To complete the configuration, please click “Close” in Fig 7-12.

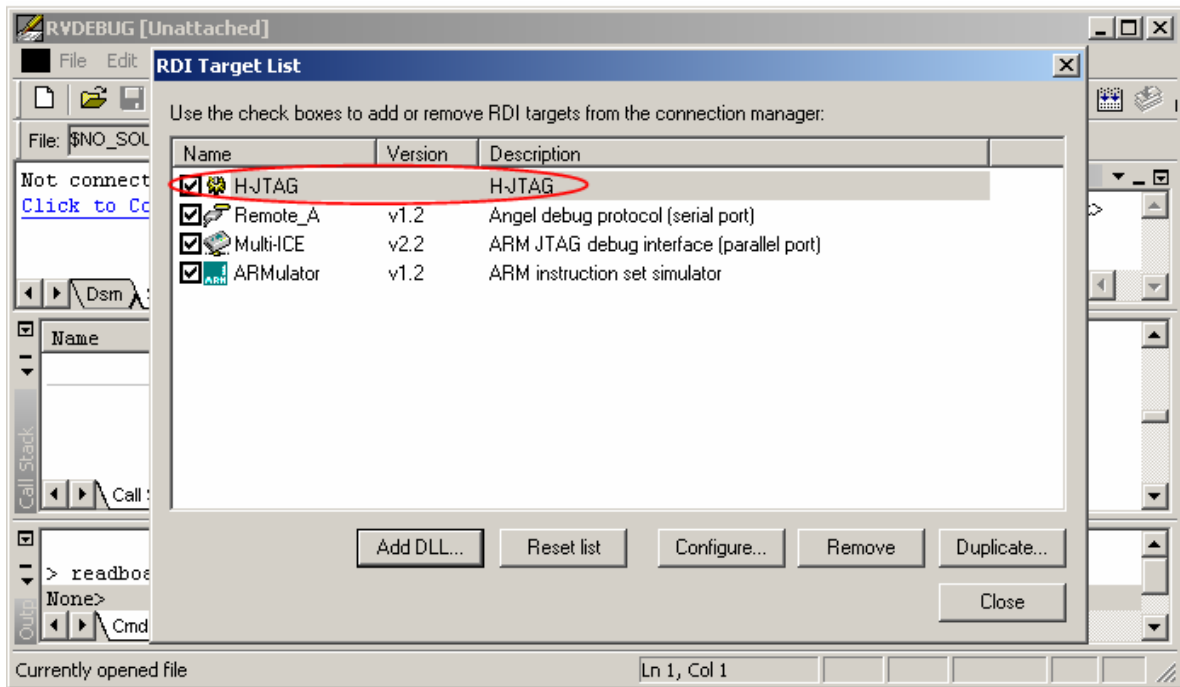


Fig 7-12 RVDS Configuration

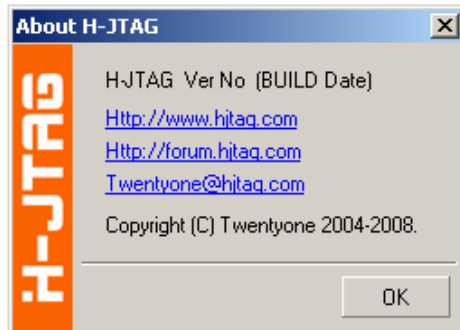


Fig 7-13 H-Jtag Information

7.3 Configure IAR

IAR stands for IAR Embedded Workbench, which is from IAR Corp. This section introduces how to configure IAR to work with H-Jtag.

First, start IAR and click Project -> Options.

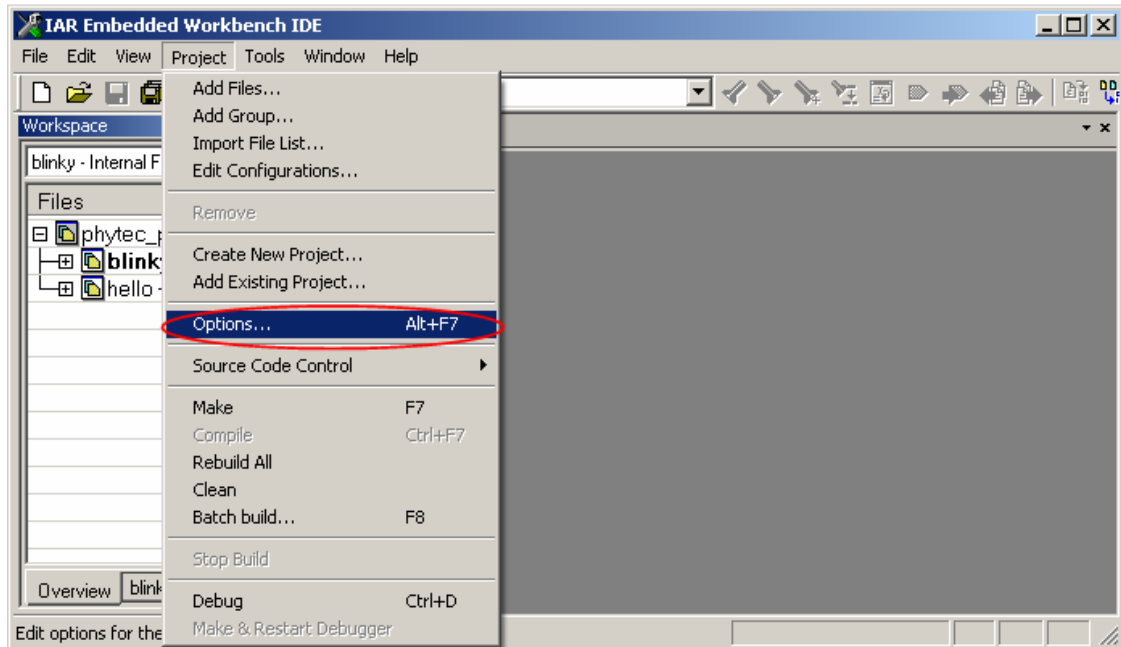


Fig 7-14 IAR Options Menu

Then, following dialog of options is shown up.

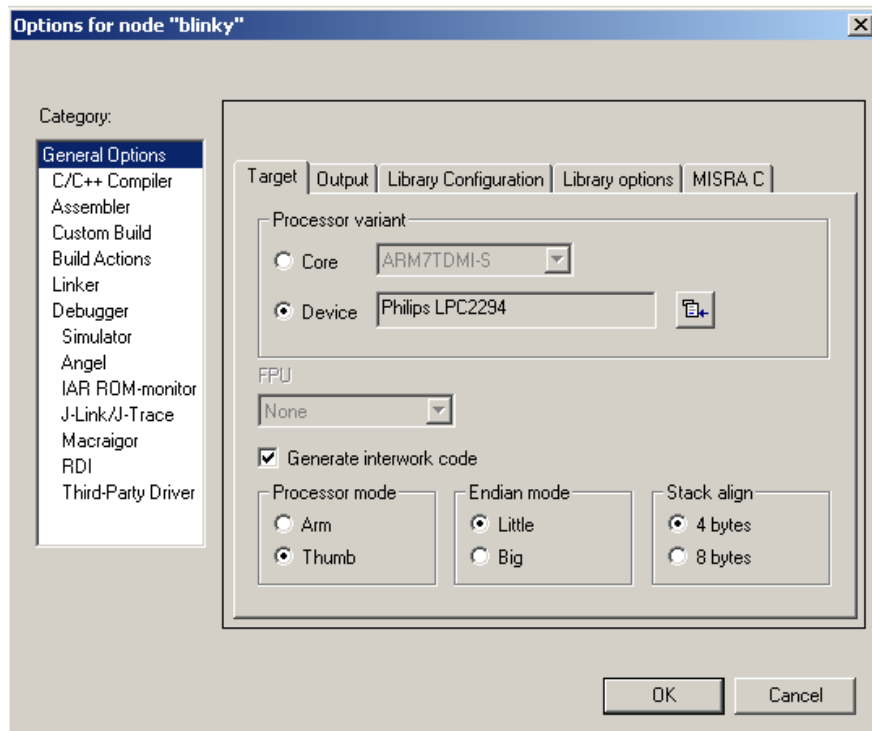


Fig 7-15 Dialog of Options

In Fig 7-15, select Debugger category and then active Setup page. In Setup page, please select RDI as the driver. After the selection, the page looks like Fig 7-16.

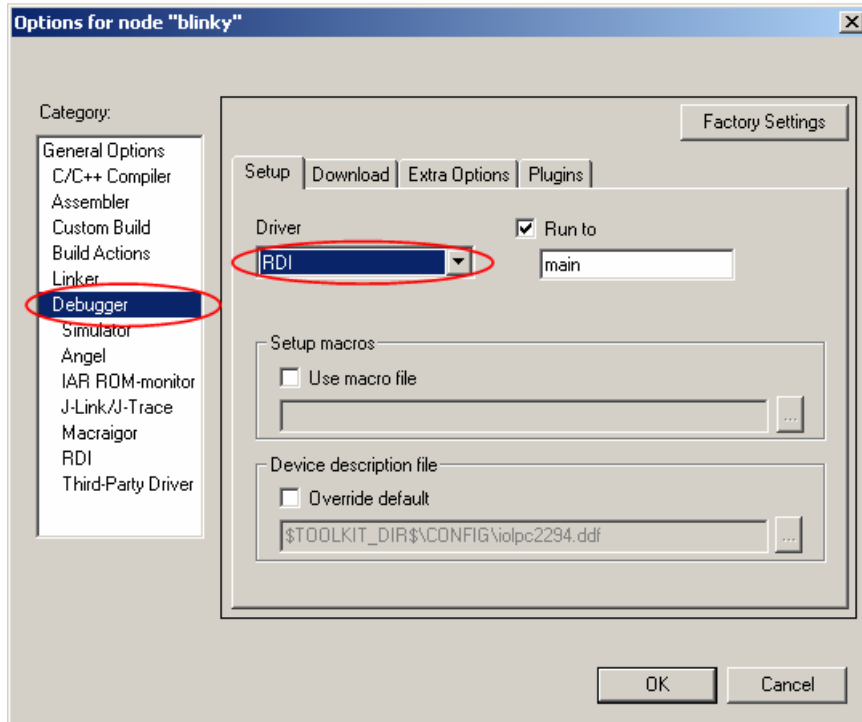


Fig 7-16 Debugger Configuration

Then select RDI category, as shown in following figure. In this page, user needs to specify the path for H-JTAG.DLL.

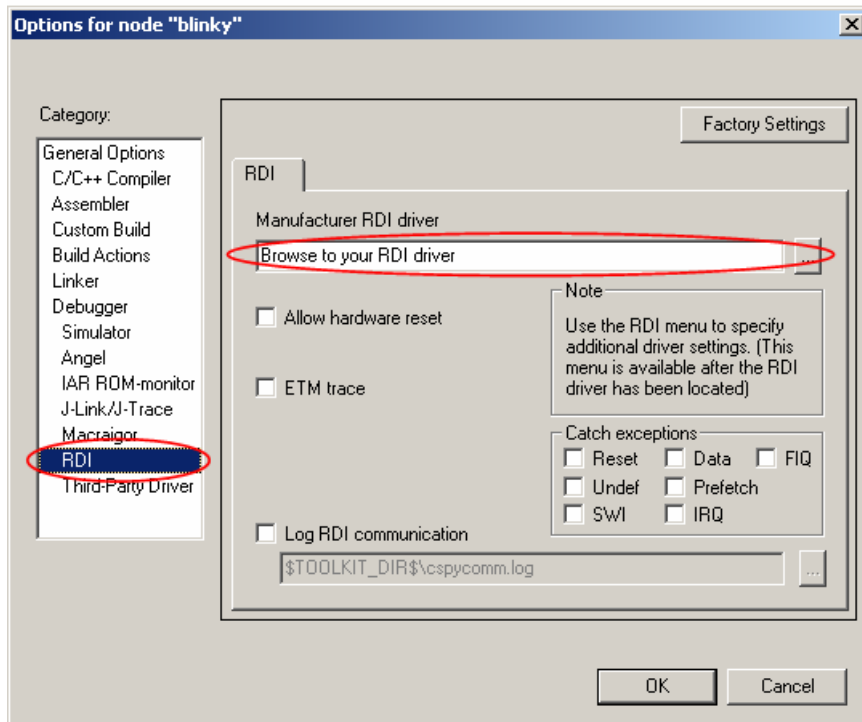


Fig 7-17 RDI Configuration

In Fig 7-17, click “Browse” and select H-JTAG.DLL located under the installation folder of H-JTAG. After this, the dialog looks like Fig 7-18.

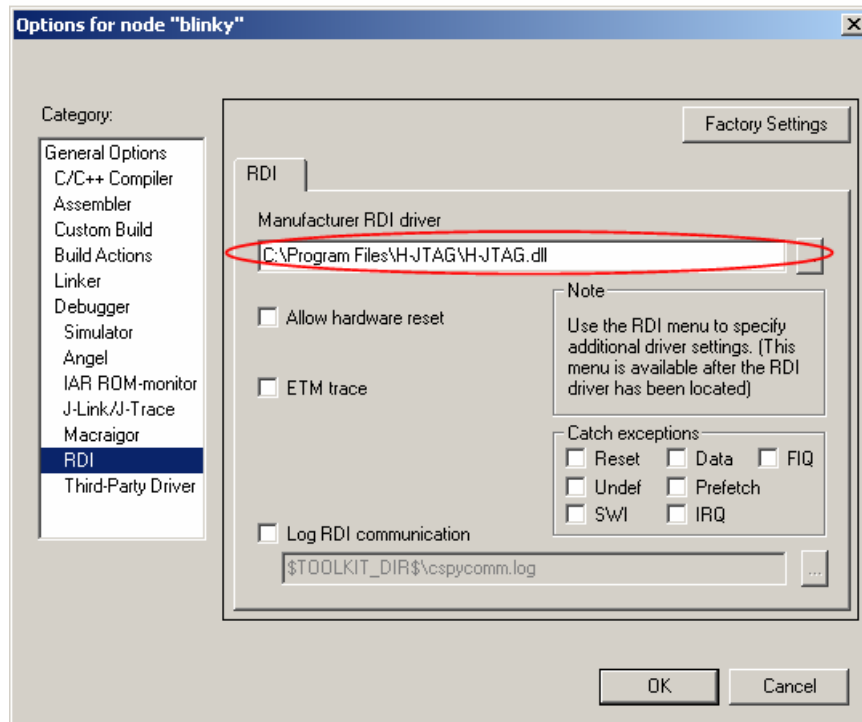


Fig 7-18 Choose H-JTAG.DLL

In above figure, click “OK” to complete the configuration. After the configuration is completed, a new menu named RDI is added in the main window, as shown in Fig 7-19. To check the basic information about H-Jtag, click RDI -> Configure. The basic information about H-Jtag is shown in Fig 7-20.

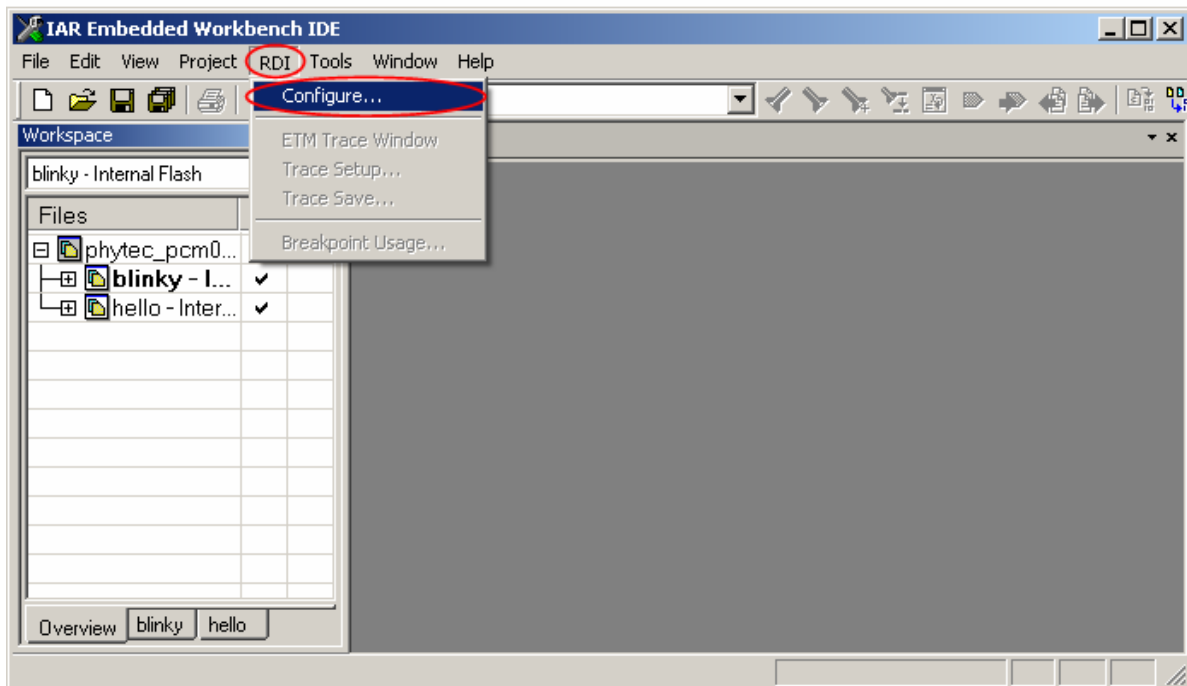


Fig 7-19 New RDI Menu

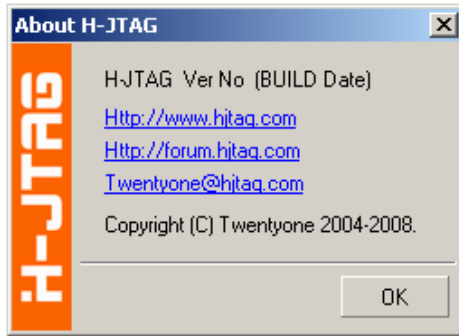


Fig 7-20 H-Jtag Information

Note:

If user wants to use auto flash download in IAR, please disable “Verify Download” and “Use Flash Loader(s)” in IAR. Fig 7-21 shows how to disable these options.

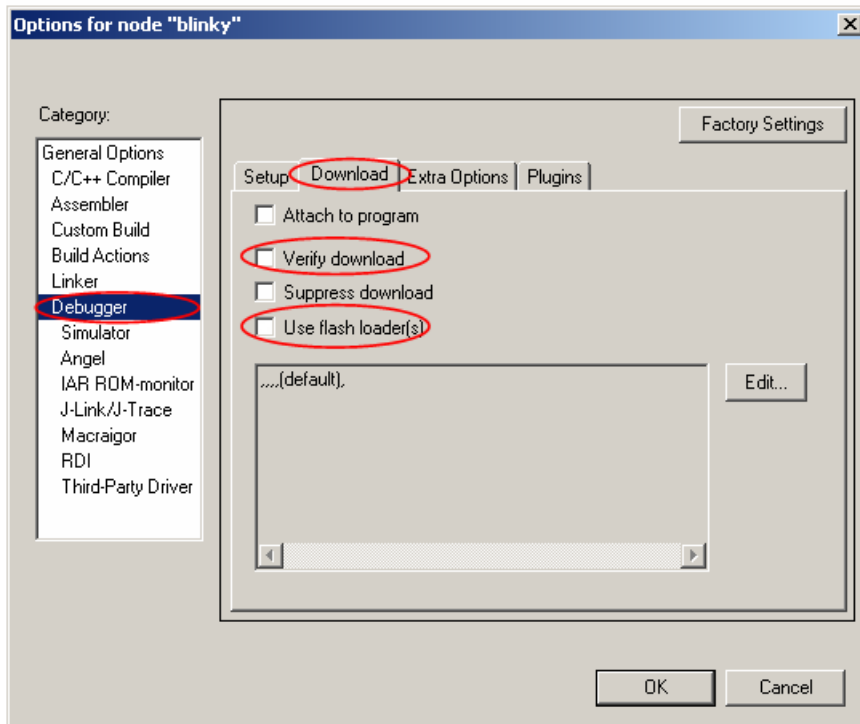


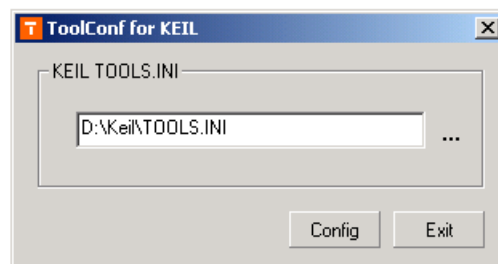
Fig 7-21 Disable Verify Download Option

7.4 Configure KEIL

KEIL for ARM is an IDE from KEIL Corp. This section introduces how to configure KEIL to work with H-Jtag

From H-JTAG V0.9.2, H-JTAG uses the AGDI interface under KEIL. The RDI interface has been disabled by H-JTAG under KEIL

First, run TOOLCONF.EXE located under the installation direction of H-JTAG. The purpose is to update the configuration file (TOOS.INI) of KEIL. In TOOLCONF.EXE, use the browse button to locate the configuration file TOOLS.INI, which can be found under the installation direction of KEIL, as shown in Fig 7-22. Then click the Config button to perform the update. After the update is completed successfully, click Exit to exit TOOLCONF.EXE.



Next, start KEIL and open a project. Then click Project -> Options for Target, as shown in Fig 7-23.

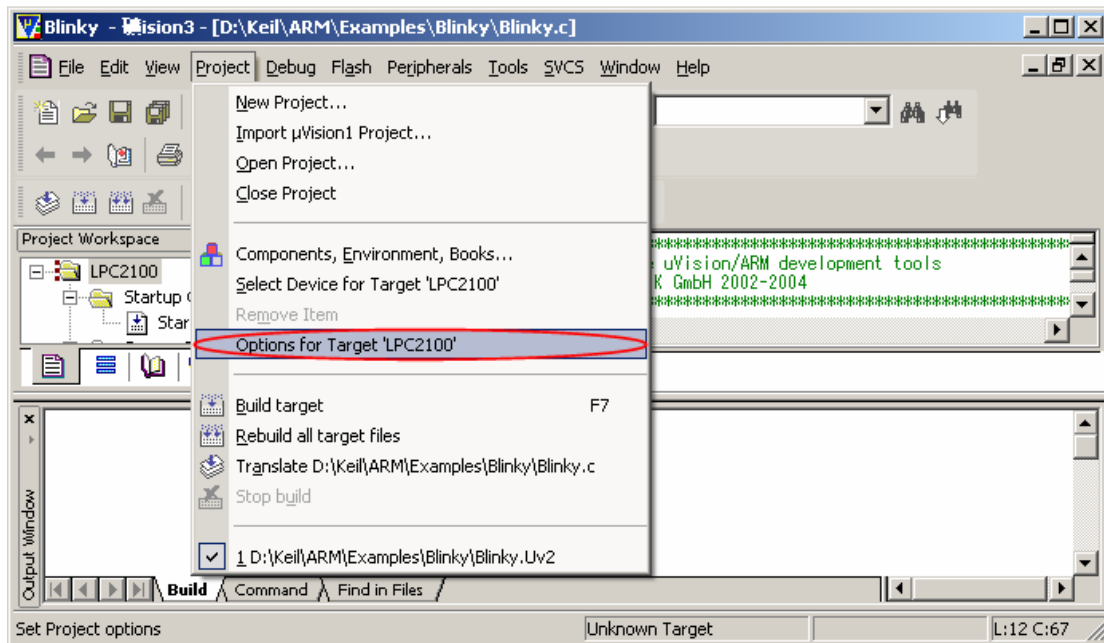


Fig 7-23 Menu of Options

Then, a dialog of options is shown up, which looks like Fig 7-24.

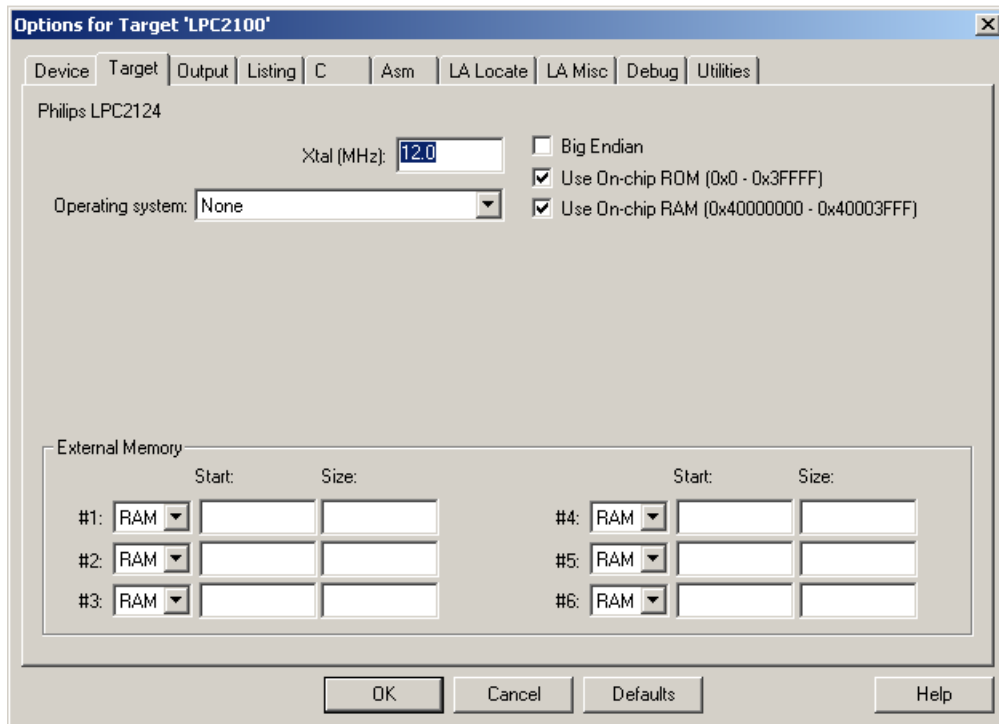


Fig 7-24 Dialog of Options

In the dialog shown in Fig 7-24, active the Debug page.

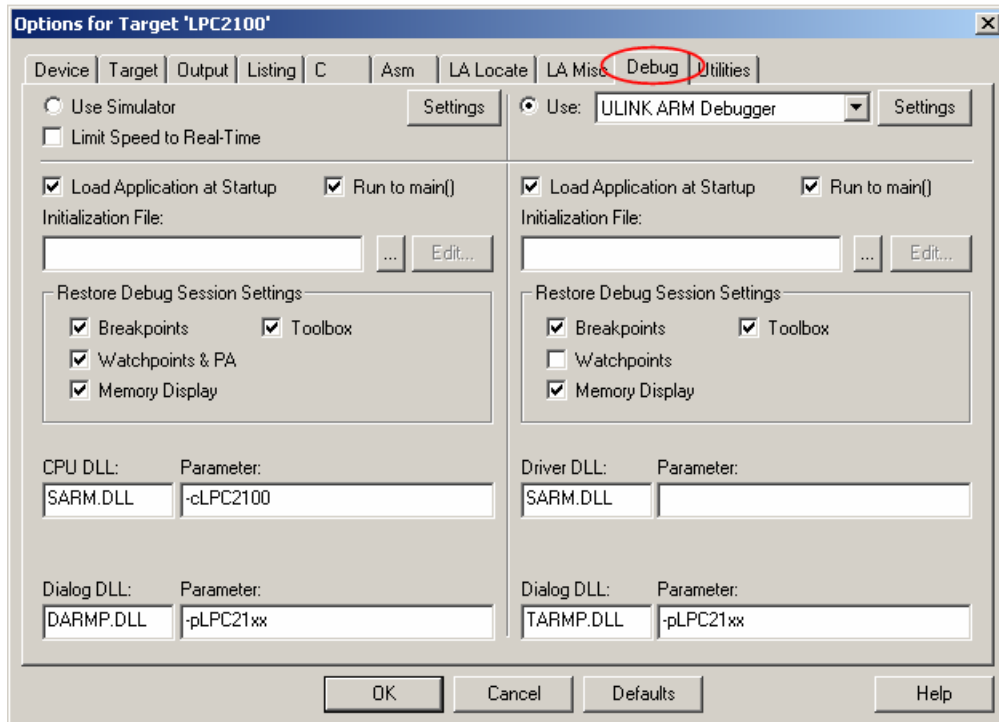


Fig 7-25 Debug Page

In the Debug page, click the drop-down button, two debug drivers, H-JTAG ARM and H-JTAG CORTEX-M3, can be found on the list, as shown in Fig 7-26. User should select one of the drivers accordingly. Then, click OK to complete the configuration.

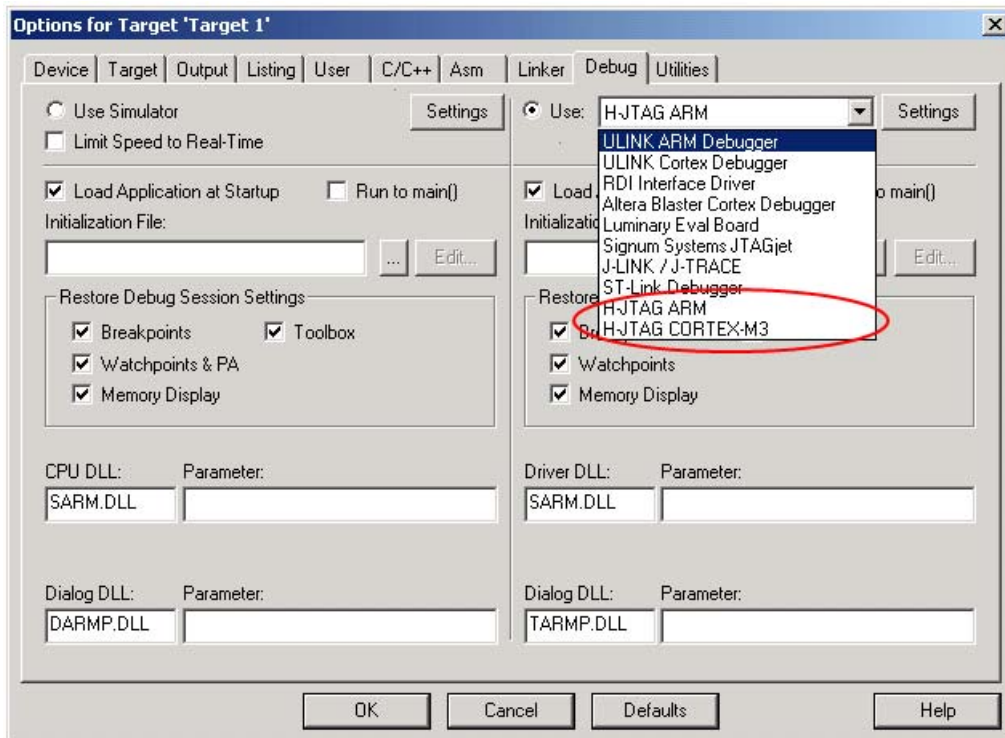


Fig 7-26 H-JTAG Debug Drivers